RESEARCH MEMORANDUM

INVESTIGATION OF SYMMETRICAL BODY INDENTATIONS DESIGNED

TO REDUCE THE TRANSONIC ZERO-LIFT WAVE DRAG OF A

45° SWEPT WING WITH AN NACA 64A006 SECTION AND

WITH A THICKENED LEADING-EDGE SECTION

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SUMMARY

This wind-tunnel investigation was conducted at Reynolds numbers of about 7,000,000 based on the mean aerodynamic chord of the wing and the tests covered a Mach number range from 0.6 to 1.2. Two airfoils of the same maximum thickness were tested to evaluate the effect of a large leading-edge radius with increased thickness over the forward 40 percent of the chord on the reliability of the predictions of the supersonic area rule. The basic wing had an aspect ratio of 3, a leading-edge sweep of 45°, a taper ratio of 0.4, and NACA 64A006 sections perpendicular to a line swept back 39.45°, the quarter-chord line of these sections. The modified wing was similar to the basic wing in plan form; however, the leading-edge radius of the modified airfoil was about five times as great as that of the basic airfoil. Both wings were tested with a fineness-ratio-12.5 Sears-Haack body and with this body indented for the respective wings for design Mach numbers of 1.05 and 1.20. The basic-wing model was also tested with the body indented for a design Mach number of 1.00.

The test results indicated that indentations designed for the modified wing were as effective in reducing the wave drag as those for the basic wing. For this investigation the leading edges of the wings were at all times subsonic or behind the Mach lines. With all the indentations tested, substantial reductions in zero-lift drag were obtained at all supersonic speeds. The M=1.05 indentations were almost as effective as the M=1.20 indentations at M=1.20, and as the M=1.00 indentation (basic wing) at M=1.00. Thus for the configurations tested the M=1.05 design probably approaches the best compromise design for the test Mach numbers. For similar or thinner wings and similar body sizes relative to the wings, the test data indicated that the wing volume exposed by indentation of the body may be neglected in designing indentations for supersonic Mach numbers; however, this additional wing volume







was included in all the wave-drag computations. The experimental dragrise coefficients were adequately predicted at all supersonic Mach numbers by theoretical computations for the models with either the basic or modified wing section.

INTRODUCTION

The wing-tunnel investigation of a thin swept wing reported in reference l illustrated how a section modification, consisting of a greatly increased leading-edge radius and slight forward camber, was effective in improving the stability, drag, and high-lift characteristics of the wing at low speeds. For the supersonic range of test Mach numbers M = 1.2 to 1.9 (ref. 1), the modification resulted in an increase of wave drag which made the modified wing inferior to the basic wing except at lift coefficients greater than 0.6. The increase in wave drag was attributed primarily to the change in area distribution.

The primary purpose of the present investigation was to determ ne if the wave-drag penalty associated with the change of area-distribution of the modified wing might be eliminated by suitable body contouring; in other words, to determine if the supersonic area-rule principles of references 2 and 3 can be successfully applied to a wing with a blunt airfoil section for speeds at which the wing leading edge is subsonic (component of velocity normal to the leading edge less than the speed of sound).

Another object of the investigation was to compare the relative merits of various indentations (each designed for a specific Mach number) in terms of average drag reduction through the transonic Mach number range. For indentations designed for M=1.20 an additional question considered was whether indentations should be designed to compensate for wing volume exposed by the indentation.

For the wind-tunnel investigation reported herein, a wing was selected with the same thickness distribution as the modified wing of reference 1, but with the camber removed to isolate the effect of the change in area distribution. The basic wing of this investigation was the same as the basic wing of reference 1. The fuselage indentations were generally designed by the procedure outlined in reference 2, and the wave-drag coefficients for each configuration were predicted by the computing procedure of reference 4.

The tests were conducted in the 14-foot transonic wind tunnel at the Ames Aeronautical Laboratory over a Mach number range of 0.6 to 1.2 at Reynolds numbers of about 7,000,000 based on the mean aerodynamic chord of the wing.

The symbols used in this report are defined in Appendix A.





WIND TUNNEL

A sectional view of the high-speed region of the Ames 14-foot transonic wind tunnel is shown in figure 1. This tunnel is of the closed return type with perforated walls in the test section. The flexible walls ahead of the test section are used to produce the convergent-divergent form required to generate supersonic Mach numbers up to 1.2.

Models are mounted by means of a sting and the forces are measured as electrical outputs from a strain-gage balance located within the model. A photograph of the model support system is shown in figure 2, which shows a rear view of the test section of the wind tunnel.

This tunnel is similar to the smaller Ames 2- by 2-foot transonic wind tunnel which is described in detail in reference 5. One exception, however, is that the l^4 -foot tunnel is not of the variable density type, but operates at atmospheric pressure.

MODELS AND TESTS

The models used in this investigation consisted of wing and body combinations of essentially the same plan form as illustrated in the dimensional sketch of figure 3. The basic body was a Sears-Haack body (body with minimum transonic drag for given volume and length) and had a closed-body fineness ratio of 12.5.

The basic wing had an aspect ratio of 3, a leading-edge sweep of 45° , a taper ratio of 0.4, and NACA 64A006 sections perpendicular to a line swept back 39.45° which was the quarter-chord line of these sections. The coordinates of this airfoil section are listed in table I with the corresponding coordinates of the streamwise section. The sweep of the streamwise quarter-chord line was 40.60° . The wing plan-form area was 8.72 square feet including the region within the body.

The modified wing had a leading-edge sweep angle of 45.30 and, in comparison with the basic wing, an airfoil with a greatly increased leading-edge radius (about five times) and with increased thickness on the forward 40 percent of the chord. These airfoil coordinates are also listed in table I. The leading-edge sweep was altered from that of the basic wing due to the increase of the streamwise length of the chords of about 2 percent. This modified wing had a symmetrical section of the same thickness distribution as the slightly cambered wing of reference 1.

Five different bodies were tested with the basic wing and four bodies with the modified wing. The body radii are listed in table II and the cross-sectional area distributions normal to the longitudinal axis are presented in figure 4.





Basic-Wing Bodies

Sears-Haack body

M = 1.00 re-indentation

M = 1.05 indentation

M = 1.20 indentation

M = 1.20 re-indentation

Modified-Wing Bodies

Sears-Haack body

M = 1.05 indentation

M = 1.20 indentation

M = 1.20 re-indentation

The indentations were of circular cross section and were designed as outlined in reference 2 by indenting for the wing volume outside the given Sears-Haack body. The M=1.00 and M=1.20 re-indentations were computed as a function of the wing volume exposed by the indentation and hence were deeper than the normal indentations. The equations used for this type computation are given in Appendix B which also outlines the procedure used to compute the wing cross-sectional areas. For very thin wings the volume exposed by the indentation may be trivial, but for the wings tested, this was not the case, as is illustrated in figures 4(e) and 4(f).

Photographs of two of the models are shown in figure 5. The modified wing with the Sears-Haack body is shown in figure 5(a) and the basic wing with the M=1.20 re-indentation is shown in figure 5(b). This re-indentation was the deepest indentation tested with the basic wing. The location of the pressure orifices for the body and the wings is presented in figures 6(a) and 6(b), respectively.

The test data included force, moment, and pressure measurements taken at angles of attack from about -4° to $+6^{\circ}$ at Mach numbers from 0.60 to 1.20. At a Mach number of 0.60 additional data were taken at higher angles of attack up to about $+9^{\circ}$. The Reynolds number per foot for these tests was almost 4,000,000 and the Reynolds number based on the mean aerodynamic chord of the basic wing varied from about 6,000,000 to 7,000,000 as shown in figure 7.

All coefficients are based on the area and the mean aerodynamic chord of the basic wing, and the pitching moments were computed about the quarter-chord point of the mean aerodynamic chord of the basic wing. Tunnel blockage for all models was less than one-half of one percent, based on either frontal area or the maximum cross-sectional area of the wing-body combinations, and the data should be relatively free of wall interference, as indicated in reference 5. The angle-of-attack data were corrected for tunnel air-stream angularity which was less than 1° for all Mach numbers. The drag data were corrected by the removal of base drag. To obtain this correction the pressure at the hollow base of each model was corrected to correspond to free-stream static pressure. As a check on this procedure for removing the base drag and as an approximate check for possible sting interference effects, the Sears-Haack body was tested without wings so that the drag data could be compared with the theoretical wave-drag value corrected for the cut-off portion of the body.





RESULTS AND DISCUSSION

The presentation of the various aerodynamic coefficients and their discussion will be in three parts: comparison of the basic-wing models with the modified-wing models, comparison of experimental and predicted zero-lift wave-drag coefficients, and comparison of indentations. Presentation of the pressure data will be secondary with emphasis primarily on their use to assist in the understanding of the drag data. Data for the model with the M = 1.00 re-indentation for the basic wing was obtained as part of another investigation and will be used in this report primarily for comparison with the results for the M = 1.05 indentation for the basic wing. (The simple M = 1.00 indentation for this wing has not been tested.) The results for the M = 1.20 re-indentations for the basic and modified wings were essentially identical to the results for normal indentations, so the presentation of the data for the re-indentations was restricted to the zero-lift drag coefficients which were slightly different. Throughout the report the experimental zero-lift drag coefficients for the various configurations are generally compared directly without taking incremental values of drag-rise coefficients, because greater confidence in the data results when it is evident that there are not any large variations in subsonic drag coefficients between models.

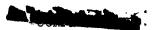
Comparison of Basic- and Modified-Wing Models

Static aerodynamic characteristics of the basic- and modified-wing models with the Sears-Haack body, the M = 1.05 indentations, and the M = 1.20 indentations are presented in figures 8, 9, and 10, respectively. Although the zero-lift drag data are of primary importance in the report, it is of interest to note first that the lift-curve slopes, stability changes, etc., are not very different for the two wings when tested with comparable bodies. For instance, the maximum lift-drag ratios for the two wings with various bodies are similar, as shown in figure 11. With the Sears-Haack body the modified-wing lift-drag ratios were equally as good as or better than the basic-wing model except at the highest test Mach number of 1.20. With the indented bodies, the modified-wing models had inferior maximum lift-drag ratios at the high subsonic speeds and at all supersonic speeds in comparison with the basic-wing models.

The zero-lift drag coefficients for the two wings with various bodies are presented in figure 12. This figure clearly indicates that at transonic speeds the zero-lift drag coefficients for the two wings are quite similar either with the Sears-Haack body or with their respectively indented bodies. Thus the indentations designed for the modified wing were fully as effective in reducing the zero-lift wave drag as those for the basic wing. An unexpected result, shown in figures 12 and 8(c), for the tests with the Sears-Haack body, is that at Mach numbers near 1 the



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modified wing had the lower drag coefficients of the two wings. At Mach numbers near 1.2, the basic-wing models had drag coefficients which were consistently lower than the comparable modified-wing models.

The zero-lift pressure-coefficient distributions are presented for the basic- and modified-wing models over one quadrant of the models (figs. 13 and 14). Figure 13 presents the scales and layout which should be used with figure 14 for orientation of the pressure curves. The vertical lines in figure 14 are at orifice locations as defined in figure 6. In the pressure distributions shown in figure 14 the stagnation pressures have not been shown. Tabulated values of pressure distribution corresponding to each curve of figure 14 are listed in table III. A few stagnation pressures are missing from table III due to either a leak or a restriction in the pressure lines; however, the stagnation pressures were similar for the two wings.

As should be expected, the pressure distribution over the forward portion of each wing was quite different, that is, the pressure distribution for the basic wing is typical of a low-drag section and the distribution for the modified wing is somewhat similar to older conventional sections. In spite of this difference between wings shown in figure 14, it is of interest to note in the same figure that the body pressure distributions for the M = 1.05 indentations are very similar for the two wings at all Mach numbers except for body locations near the wing leading-edge juncture with the body.

Although this presentation (fig. 14) of the pressure data illustrates primarily the difference between wings, the favorable effects of the indentations, which will be discussed later, are particularly evident on the bodies and evident to some extent over the entire wing span.

Another comparison of the differences in the sections of the two wings can be made by plotting the pressure data in a different manner, as shown by a few examples in figure 15. These curves compare the basicand modified-wing pressure coefficients at one spanwise station (0.51 b/2). The shaded regions are effectively thrust or drag parameters as defined by the equation

$$\frac{c}{z_{max}} C_{D_O} = \oint C_p \frac{dz}{z_{max}}$$

The thrust is defined in this case merely as negative drag. The pressure drag coefficient for the section can be obtained by multiplying the net area by half the maximum wing thickness and dividing by the local chord. For the curves shown in figure 15, it is evident for the representative spanwise station selected that the basic wing does not have any thrust at supersonic speeds. The basic wing on the body indented for M = 1.05





had a marked reduction of the section-pressure drag (fig. 15(c)) in comparison with this wing on the basic body (fig. 15(a)). A similar comparison for the modified wing models shows a marked increase in the thrust area as a result of the indentation. These curves also show that a large portion of the thrust area of the modified wing is offset by the drag area.

The similarity of the present zero-lift drag data for the basic and modified wings with the Sears-Haack body is somewhat in disagreement with the supersonic data from reference 1, which indicated a larger penalty in wave drag due to the modification of reference 1. (The data of reference 1 for M = 1.20 are relatively inaccurate because of large effects of reflected shock waves.) The zero-lift drag-rise coefficients for the two tests are compared in figure 16. The drag-rise coefficients were obtained by subtracting the subsonic zero-lift data at M = 0.8 from the zero-lift data at all higher Mach numbers. The friction-drag coefficient variation with Mach number was not considered, because it would be similar for the two wings and small for Mach numbers less than 1.2. Theoretical wave-drag coefficients were computed for the transonic speeds by the method of reference 4, and the solutions were limited to 25 terms; that is. effectively 25 harmonics of a Fourier sine series were used to represent the derivative of the area curves. The modification investigated in reference 1 included a slight amount of forward camber in the wing design but the airfoils had the same leading-edge radius and thickness distribution as those of the present investigation. The effect of the camber on the wave-drag coefficient was estimated in reference 6 as roughly 0.0015 at M = 1.5 and 0.0011 at M = 1.9. The difference in the Reynolds numbers of the tests might account for some of the drag difference; however, the data of reference 7 indicated that fixing transition had only a secondary effect on the drag-rise coefficients although a primary effect on the drag coefficients. For the large, unpolished models of the present tests the results are more equivalent to the transition-fixed data. The theoretical wave-drag coefficients tend to substantiate the data of the present report and will be discussed in detail in the next section of the report. It is reasonable to expect that the drag-rise coefficients due to the modification will increase at Mach numbers greater than those tested (Mach numbers for which the wing leading edge is sonic or supersonic); however, the transonic data indicate that the penalty for this modification is less than the penalty incurred through the modification tested in reference 1.

Comparison of Experimental and Computed Drag Coefficients

Experimental and theoretical (ref. 4) zero-lift drag coefficients are presented in figures 17 through 19. The effects of the various body indentations with the basic wing are shown in figure 17(a), and those with the modified wing in figure 17(b). Comparable zero-lift drag



coefficients for the two wings with the M = 1.20 re-indented bodies are presented in figure 18. The experimental data points (figs. 17 and 18) are essentially forebody data (i.e., drag coefficients for the wing and the body ahead of the model base) since the base drag has been removed. An illustrative plot of this procedure for removing the base-drag coefficients is shown in figure 19 for the test of the Sears-Haack body without a wing. The base-drag coefficients are based on the wing area and are fairly representative of the data obtained with all the models. Any possible effects of sting interference are evidently small since they are probably within the magnitude of the indicated differences between the computed and experimental forebody results of figure 19.

The theoretical wave-drag coefficients (figs. 17, 18, and 19) were computed by the method of reference 4 and were plotted as increments above the subsonic level of the experimental data near a Mach number of 0.8. As mentioned previously, the variation in friction-drag coefficients with Mach number is slight for this Mach number range and was neglected for these comparisons. The theory used in these computations requires that the area curves have zero slope at both ends of the body. For this investigation, the coefficients were computed from area-distribution curves for models with Sears-Heack bodies to closure, as shown by the area curves of figure 4. The computed wave-drag coefficients were then corrected by subtracting the estimated contribution of the cut-off portion. This small correction ($C_{\mathrm{D}_{\mathrm{O}}}$ = 0.0006) is comparable to that used in reference 6 but was estimated by a different procedure. In this case a supersonic pressure distribution for M = 1.20 was computed for the Sears-Haack body using the method of reference 8, and this pressure curve was used to evaluate the drag contribution of the cut-off portion of the body.

In general, the agreement of the computed values of zero-lift drag coefficients with the experimental results is very good. Even in the two cases where the agreement was the poorest (basic wing with the M=1.00 re-indented body, fig. 17(a) and the modified wing with the M=1.20 re-indented body, fig. 18), the trends in the experimental data were approximated by the theoretical computations. There is some indication that the experimental data points at M=1.075 are consistently high, and perhaps a little low at M=1.05 (figs. 17 and 18). Detailed calibration of the tunnel is not yet completed, but the schlieren pictures at these two Mach numbers did indicate the presence of weak reflected shocks. These reflected shocks are known to be weak due to the lack of a positive identification in any of the pressure data as shown in figure 1^4 .

A comparative evaluation of the wave-drag predictions for the two wings with the Sears-Haack body and with the indented bodies, including the effect of the airfoil modification, is shown in figure 20. A comparison is made in this bar graph of the experimental drag-rise coefficients with the predicted wave-drag coefficients at a Mach number of 1.00 and at the two design Mach numbers, 1.05 and 1.20. The shortest bar of





the four at each Mach number is the goal sought by body contouring, that is, wave-drag for a wing-body combination which is no greater than the drag of an optimized body-alone shape. For bodies with circular crosssections, this goal is probably attainable only at M = 1.00. The longest bar of the four at each Mach number is the computed wave-drag coefficient for the wings with the uncontoured Sears-Haack body. The crosshatched increment is the computed additional drag coefficient due to the wing modification. The middle two bars at each Mach number are the expected results with indented bodies. Note that the indented models designed for a specific Mach number have the lowest predicted wave drag at that Mach number, and the predicted additional drag due to the wing modification is essentially zero. Generally, the experimental results confirmed the predicted bar graphs with two interesting exceptions at M = 1.00. Agreement at M = 1.00 was not expected because the linearized theory is invalidated at this Mach number. The first exception was that the modified-wing models with the Sears-Haack body had lower, not higher, drag-rise coefficients. This effect was partially substantiated by the pressure data. The second exception, as noted in prior investigations such as reference 6, was that the predictions are pessimistically high at M = 1.00. It is also of interest to note that at M = 1.20 the predicted differences in $\Delta C_{\mathrm{D}_{\mathrm{O}}}$ between the indentations for M = 1.05 and M = 1.20 were not realized due to underestimating the experimental results in one case and overestimating them in the other. However, a designer might select the M = 1.05 indentation for this Mach number range, even without the more favorable experimental results, if the airplane had severe acceleration requirements for transonic Mach numbers.

A further evaluation of the theoretical computations is given in figure 21. This figure shows the comparison between the given areadistribution curves (modified-wing model with M = 1.05 indented body) and the computed check solutions for 25 harmonics. The area curves for the five cutting angles, θ , used in the M = 1.20 computation of the wave drag for this one model are shown. The agreement of the check solutions with the original area curves is considered to be satisfactory, considering that the boundary-layer displacement thickness was neglected in forming the area curves used in the theory. In addition, reference 4 has indicated that the use of a larger number of harmonics may not be realistic and may give poorer agreement with experimental results. In order to compare the variation of the area curves used in the theoretical computations, most of the area curves are shown at a reduced scale in figure 22. The curves for the M = 1.20 computations for $\theta = 70^{\circ}$ are deleted for clarity between curves.

Comparison of Indentations

The re-indentations for M = 1.20 in comparison with the indentations for M = 1.20 resulted in similar or higher zero-lift drag coefficients at



all Mach numbers for both the basic- and modified-wing models, as shown in figure 23. Part of the increased drag of the re-indented models is apparently due to a slight increase in friction drag. With the modified wing the re-indentations resulted in drag coefficients which were slightly higher even at the design Mach number of 1.20. As described in detail in Appendix B and mentioned previously, these re-indentations are designed as a function of the entire exposed wing volume including that wing volume exposed by the indentation. The comparison of these experimental results with theory was given previously in figures 17 and 18 and good agreement is shown for the models with the basic wing. The computed wave-drag coefficients for the re-indentations were only slightly lower than those for the normal indentations at the design Mach number of 1.20 ($C_{\mathrm{D}_{\mathrm{O}}}$ = 0.0001 and 0.0003 less than the normal indentations, basic- and modified-wing models, respectively) and were higher at all other Mach numbers. Thus the experimental and the computed data indicate that the added wing volume due to the indentation (for similar or thinner wings and similar relative body sizes) can be neglected in designing indentations, since at the design Mach number it makes little difference whether the first or second approximation to the indentation is made. However, in all cases the added wing area at each station was included in the total area curves when the wave-drag computations were made.

The effects of the various indentations on the experimental zero-lift drag coefficients are compared in figure 24 for the basic- and modifiedwing models. For all the indentations tested, substantial reductions in zero-lift drag were obtained at all the supersonic speeds. The M = 1.20indentations for the two wings resulted in substantial reductions in drag coefficients of 0.0045 to 0.0070 at all supersonic speeds tested and, as predicted by the theory, the lowest drag at M = 1.20. The M = 1.00re-indentation for the basic-wing model was successful in reducing the drag coefficients as intended at M = 1.00. However, for the configurations tested the M = 1.05 indentations were practically as effective as the M = 1.20 indentations at M = 1.20 and as the M = 1.00 re-indentation (basic wing) at M = 1.00. Thus this M = 1.05 design is close to the best compromise design for the test Mach number range and for symmetrical body contouring. The M = 1.05 body indentation for the modified wing resulted in the largest reduction in zero-lift drag coefficient (0.0100 at M = 1.05). The corresponding reduction for the basic-wing model was somewhat less, although the basic-wing model generally had slightly lower drag coefficients.

The general superiority of the M=1.05 indentations at supersonic speeds is also evident in the maximum lift-drag ratios presented in figure 25. All indentations improved the lift-drag ratios at supersonic test speeds in comparison with the values with the Sears-Haack body. The comparison between the lift-drag ratios for the two wings has been discussed previously.





The effect of the M=1.05 and M=1.20 body indentations on the lift-curve slopes at low angles of attack where the curves are linear are shown in figure 26. The M=1.20 indentations resulted in an increase in lift-curve slope at the higher supersonic speeds, but a decrease at M=1.00 and all subsonic speeds. The M=1.05 indentations resulted in greater decreases in lift-curve slope at most subsonic speeds, but also greater increases at all supersonic test Mach numbers including Mach numbers near 1.

The effect on the variation of aerodynamic-center position due to the M=1.05 and M=1.20 indentations was primarily a delay in the rearward shift of the aerodynamic-center position with Mach number, as shown in figure 27; however, the indented models had the largest shift in going from subsonic to supersonic speeds.

SUMMARY OF RESULTS

The main results of this investigation are as follows:

- 1. The indentations designed for the modified wing with a thickened leading edge were as effective in reducing the wave drag as those for the basic wing, particularly at zero lift and at the design Mach number of the indentation.
- 2. At transonic speeds the zero-lift drag coefficients for the two wings were similar; however, at Mach numbers near 1.2 the basic-wing models consistently had drag coefficients which were lower than modified-wing models with the Sears-Haack body or with indentations designed for the same Mach number.
- 3. The M=1.05 indentations were practically as effective as the M=1.20 indentations at M=1.20 and as the M=1.00 indentation (basic wing) at M=1.00. Thus for the configurations tested the M=1.05 design is probably the best compromise design for the test Mach number range.
- 4. For similar or thinner wings and similar body sizes relative to the wings, the wing volume exposed by indentation of the body may be neglected in designing indentations for a supersonic Mach number; however, this additional wing volume was included in all the wave-drag computations.
- 5. The experimental wave-drag coefficients were adequately predicted in each case at all supersonic Mach numbers.

Ames Aeronautical Laboratory
National Advisory Committee for Aeronautics
Moffett Field, Calif., Nov. 26, 1956



APPENDIX A

SYMBOLS

A aspect ratio, $\frac{2b}{(1+\lambda)c_{\sigma}}$

a dimensionless parameter, $\frac{1}{1-\frac{\tan\,\Omega_{\mathrm{TE}}}{\tan\,\Omega_{\mathrm{LE}}}}$ or

$$\left(\frac{\underline{x}}{\underline{c}}\right)_{\text{ref}} + \frac{\underline{A}}{\underline{I}_{+}} \left(\frac{\underline{1} + \lambda}{\underline{1} - \lambda}\right) (\text{tan } \Lambda_{\text{ref}} \text{-tan } \psi)$$

b model span

 C_{D} drag coefficient

 ${\tt C}_{{\tt D}_{\smallfrown}}$ zero-lift drag coefficient

 $\Delta {\rm C_{\rm D_{\rm O}}}$ rise of ${\rm C_{\rm D_{\rm O}}}$ above subsonic level (M ~ 0.8)

C_{T.} lift coefficient

 C_{m} pitching-moment coefficient about $\frac{\overline{c}}{h}$ for the basic wing

 C_p pressure coefficient, $\frac{p-p_{\infty}}{q}$

c local chord of wing measured parallel to the plane of symmetry

co local chord, c, at intersection of area cut with leading or trailing edge, whichever is the greater distance from the center line

(The edges are considered as extending to their point of intersection.)

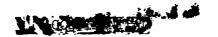
mean aerodynamic chord of the total basic wing

c' local chord of the design airfoil sections

e perpendicular distance from co to center line

 $\left(\frac{L}{D}\right)_{max}$ maximum lift-drag ratio





M	free-stream Mach number
N	number of terms or harmonics used in the theoretical computations of wave drag
p	local static pressure on the model
p_{∞}	free-stream static pressure
q	free-stream dynamic pressure
R	Reynolds number
r	perpendicular distance from edge of body to center line; radius of body
S	projection of S_8 on a plane perpendicular to x axis
Ss	area formed by cutting configurations with planes tangent to the Mach cone
s_{w}	total wing area including the region within the body
S(§)	at \$, the cross-sectional wing area projected on a plane perpendicular to the x axis
t	local wing thickness
$\left[\frac{\mathbf{t}}{\mathbf{c}}\right]$	normalized thickness-chord ratio, $\frac{t/c}{(t/c)_{\sigma_{max}}}$
x	planes tangent to the Mach cone
x,y,z	Cartesian coordinates as conventional body axes
x t	distance from the wing leading edge to a point in the wing-chord plane measured in the x direction
y †	distance from c_{O} to a point in the wing-chord plane measured in the negative y direction
α	angle of attack
γ	constant ratio of thicknesses, $\frac{t_T}{t_\sigma}$ at a given percent chord nondimensionalized variable of integration, $\left(\frac{y^i}{c_O}\right)$ tan $\Omega_{\rm LE}$
η	nondimensionalized variable of integration, $\left(\frac{y^i}{c}\right)$ tan Ω_{IE}
	(integration from wing extremities to plan-form center line)

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 $\eta_e^{-\eta}_{b/2}$ for



η_{B}	limit of integration, at the body, $\eta_{\rm e}^{-\eta}_{\rm r}$
$\eta_{_{\mathrm{T}}}$	limit of integration, at the wing tip, equals
	$\eta_{b/2} < \eta_e$ and 0 for $\eta_{b/2} \ge \eta_e$

 θ angle between the z axis and the intersection of the cutting plane X with the yz plane

 Λ_{LE} leading-edge sweep

 Λ_{TR} trailing-edge sweep

 $\Lambda_{ ext{ref}}$ reference percent-chord-line sweep

 λ taper ratio, $\frac{c_{\tau}}{c_{\sigma}}$

distance in the x direction measured from the intersection of the configuration center line and the wing leading edge

wangle in the xy plane between the intercept of the cutting planes X with the xy plane and the positive y axis, $\arctan(\sqrt{M^2-1} \cos \theta)$

 $\Omega_{\text{T.E.}}$ sheared-wing leading-edge sweep, $\arctan(\tan \Lambda_{\text{LE}} - \tan \psi)$

 Ω_{TPE} sheared-wing trailing-edge sweep, $\arctan(\tan \Lambda_{TPE}-\tan \psi)$

Subscripts

i indentation

max maximum value

ref reference percent chord line

σ body center-line location

τ wing tip location





APPENDIX B

COMPUTATION OF WING CROSS-SECTIONAL AREAS

AND RE-INDENTATIONS

A wing cross-sectional-area computation procedure applicable to wings of any sweep and any normal taper ratio $(0 \le \lambda \le 1)$ is presented. The procedure is, to a large extent, based on the work of Jarmolow and Vandrey, reference 9. The equations are written primarily for wings with straightline surface elements along a constant-percent-chord location. The airfoil section at the center of the wing may be similar or different from the tip airfoil section. An equation is also presented for a wing with linear thickness-ratio variations.

Indentation formulas which include the added wing area due to the indentation (re-indentation) are written for a Mach number of 1.00 and for supersonic Mach numbers. These equations are approximations, but are considered entirely satisfactory for thin wings and for indentations that are not too abrupt.

COMPUTATION OF WING CROSS-SECTIONAL AREAS

General Area Equation for Wings With Linear Variation of Physical Thickness

The general equation in nondimensionalized form, which is derived later in this appendix, is:

$$\frac{S(\xi)}{c_{\sigma}^{2}} = K\left(\frac{c_{o}}{c_{\sigma}}\right)_{\xi} \int_{\eta_{1}}^{\eta_{2}} f_{1}(\eta) \left\{ 1 - \left[1 - \lambda f_{2}(\eta)\right] \frac{\eta_{e} - \eta}{\eta_{b/2}} \right\} d\eta \tag{1}$$

where

$$K = \frac{(t/c)_{\sigma_{\text{max}}}}{\tan \Omega_{\text{T.F.}}}$$

$$f_1(\eta) = \begin{bmatrix} \frac{t}{c} \end{bmatrix}_{\sigma} = \text{normalized thickness-chord ratio along center-line chord}$$

$$(\text{varies with percent chord, a function of } \eta)$$

$$f_2(\eta) = \frac{[t/e]_{\tau}}{[t/e]_{\sigma}}$$



 $\left[\frac{t}{c}\right]_{T}$ = normalized thickness-chord ratio along tip chord (varies with percent chord, a function of η)

The equation gives the wing cross-sectional area at each station ξ , along the center line; η is the variable; for each ξ , c_0 is a constant; however, c_0 is a function of ξ .

Equation (1) can be used for any Mach number. For Mach number 1.00 the wing plan form is handled directly; however, for Mach numbers greater than 1, the symbol, tan $\Omega_{\rm LE}$ includes the effect of "shearing" the M > 1 wing to an equivalent M = 1 wing. (See following discussion and definitions in fig. 28 and Appendix A.)

For Mach number 1.00, the wing-area cuts are perpendicular to the x axis (fig. 28(a)). One computation of wing cross-sectional area at each station, ξ , is all that is needed. For Mach numbers greater than 1.00, the Mach planes will no longer cut the wing perpendicular to the x axis. If the wing is considered to lie within the xy plane, for Mach numbers greater than 1.00, the Mach planes tangent to the Mach cone will cut the wing not only at the angle, $\psi = \arctan\sqrt{M^2-1}$, but also at smaller angles, $\psi = \arctan\sqrt{M^2-1}\cos\theta$, (due to planes tangent to the Mach cone along a line not in the xy plane). In order to compute the complete drag for one Mach number, M > 1, the areas at various roll angles θ should be computed. (See ref. 4.)

The equations have been worked out for planes cutting a wing perpendicular to the x axis. For M=1.00, then, the cutting planes are in the proper position. For Mach numbers greater than 1.00, the shearing technique of reference 9 was used to make all cutting planes perpendicular to the x axis. The wings can be sheared such that the resulting area perpendicular to the x axis is an area equivalent to the projection of the oblique cut on the yz plane. Thus, the procedure is to shear the wings and compute the area perpendicular to the x axis as in the M=1.00 case. The shearing is defined in figure 28(b). This shearing will also affect the wing plan-form parameter a since a is a function of the angles shown. The sheared wing will have a new leading-edge angle,

 $\Omega_{T,E} = \arctan(\tan \Lambda_{T,E} - \tan \psi)$

and a new trailing-edge angle

 $\Omega_{\text{rpg}} = \arctan(\tan \Lambda_{\text{rpg}} - \tan \psi)$

For M=1.00, tan ψ is zero. Note that tan ψ is a function of the Mach number and the cosine of the roll angle, and as $\cos\theta$ changes from plus to minus, tan ψ will also change.





In this analysis the wing thickness has been considered as lying in the xy plane. This concept introduces an error in the vertical direction for Mach numbers greater than 1.00. However, this error is considered insignificant for thin wings $((t/c)_{\max} = 0.06 \text{ or less})$.

The equation for computing areas for wings with linear spanwise variation in thickness along constant-percent-chord lines will be developed from the simple area integral equation. With this linear thickness variation the wing surface is composed of straight-line elements. The cross-sectional area at one longitudinal station, §, may be written as

$$S(\xi) = \int t \, dy'$$
 (2)

where y' is taken in the opposite direction to y and is measured from the spanwise station at which the chord length is c_0 . One may write a new variable of integration, η , by nondimensionalizing y' as follows:

$$\eta = \frac{y'}{c_0} \tan \Omega_{IF} \tag{3}$$

For M = 1.00 cuts $\eta = \frac{y^2}{c_0} \tan \Lambda_{\underline{I}\underline{F}}$ which is similar to the notation of reference 9.

The thickness, t, at any point on the wing plan form will be expressed as a function of the thickness at the center of the wing, t_{σ} , and the thickness at the tip, t_{τ} ; and t_{τ} and t_{σ} will be the thickness on the percent-chord line passing through this point (fig. 28(a)). At any percent-chord station:

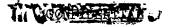
$$t = t_{\sigma} - (t_{\sigma} - t_{\tau}) \frac{\Delta y^{\dagger}}{b/2}$$

where, from equation (3) and figure 28,

$$\frac{\Delta y^{t}}{b/2} = \frac{e-y^{t}}{b/2} = \frac{\eta_{e} - \eta}{\eta_{b/2}}$$

and thus

$$t = t_{\sigma} - (t_{\sigma} - t_{\tau}) \frac{\eta_{e} - \eta}{\eta_{h/2}}$$
 (4)





The chord, c, at any point can be expressed as a function of the chord, c_0 , located at the intersection of the area cut and the outer edge of the wing (extended if necessary), figure 28, and as a function of the tangents at the leading and trailing edges.

$$c = c_0 + y'(\tan \Lambda_{IE} - \tan \Lambda_{TE}) = c_0 \left(1 + \frac{\eta}{a}\right)$$
 (5)

Note that a change in $\tan \psi$ does not affect the chord, c. An expression for the <u>ratio</u> of <u>thickness</u> to <u>chord</u> can be obtained by combining equations (4) and (5) and introducing \mathbf{c}_{σ} .

$$\frac{\mathbf{t}}{\mathbf{c}} = \frac{\mathbf{c}_{\sigma}}{\mathbf{c}_{\sigma}[1 + (\eta/a)]} \left[\frac{\mathbf{t}_{\sigma}}{\mathbf{c}_{\sigma}} - \left(\frac{\mathbf{t}_{\sigma}}{\mathbf{c}_{\sigma}} - \frac{\mathbf{t}_{\tau}}{\mathbf{c}_{\sigma}} \right) \frac{\eta_{e} - \eta}{\eta_{b/2}} \right]$$

and since

$$\frac{\mathbf{t}_{\mathsf{T}}}{\mathbf{c}_{\mathsf{G}}} \frac{\mathbf{c}_{\mathsf{T}}}{\mathbf{c}_{\mathsf{T}}} = \frac{\mathbf{t}_{\mathsf{T}}}{\mathbf{c}_{\mathsf{T}}} \frac{\mathbf{c}_{\mathsf{T}}}{\mathbf{c}_{\mathsf{G}}} = \frac{\mathbf{t}_{\mathsf{T}}}{\mathbf{c}_{\mathsf{T}}} \lambda$$

then

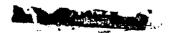
$$\frac{\mathbf{t}}{\mathbf{c}} = \frac{\mathbf{c}_{\sigma}}{\mathbf{c}_{o}[1 + (\eta/\mathbf{a})]} \left[\frac{\mathbf{t}_{\sigma}}{\mathbf{c}_{\sigma}} - \left(\frac{\mathbf{t}_{\sigma}}{\mathbf{c}_{\sigma}} - \lambda \frac{\mathbf{t}_{\tau}}{\mathbf{c}_{\tau}} \right) \frac{\eta_{e} - \eta}{\eta_{b/2}} \right]$$
(6)

The <u>normalized thickness ratio</u> is the ratio of thickness-to-chord ratio at any point, to the maximum thickness-to-chord ratio at the center line; the normalized thickness ratio will range between 0 and 1 unless the tip airfoil section has the greater maximum thickness-to-chord ratio. By definition,

$$\left[\frac{t}{c}\right] = \frac{t/c}{\left(t/c\right)_{\sigma_{\text{max}}}} \tag{7}$$

then

$$\left[\frac{t}{c}\right]_{\tau} = \frac{(t/c)_{\tau}}{(t/c)_{\sigma_{\text{max}}}}; \quad \left[\frac{t}{c}\right]_{\sigma} = \frac{(t/c)_{\sigma}}{(t/c)_{\sigma_{\text{max}}}}; \text{ etc.}$$





$$\left[\frac{t}{c}\right] = \frac{c_{\sigma}}{c_{o}} \left(\left[\frac{t}{c}\right]_{\sigma} - \left\{ \left[\frac{t}{c}\right]_{\sigma} - \lambda \left[\frac{t}{c}\right]_{T} \right\} \frac{\eta_{e} - \eta}{\eta_{b/2}} \right) \frac{1}{1 + (\eta/a)}$$

then from definitions given with equation (1),

$$\left[\frac{\mathbf{t}}{\mathbf{c}}\right] = \frac{\mathbf{c}_{\sigma}}{\mathbf{c}_{o}} \, \mathbf{f}_{1}(\eta) \left\{ 1 - \left[1 - \lambda \mathbf{f}_{2}(\eta)\right] \, \frac{\eta_{e} - \eta}{\eta_{b/2}} \right\} \frac{1}{1 + (\eta/a)} \tag{8}$$

The final equation (eq. (1)) is obtained by substituting equations (3), (5), (7), and (8) in equation (2) and nondimensionalizing with the center-line chord,

$$\frac{S(\xi)}{c_{0}^{2}} = \frac{\left(c_{0}/c_{0}\right)_{\xi}(t/c)_{\sigma_{max}}}{\tan \ \Omega_{LE}} \int_{\eta_{L}}^{\eta_{2}} f_{1}(\eta) \left\{1 - \left[1 - \lambda f_{2}(\eta)\right] \frac{\eta_{e} - \eta}{\eta_{b/2}}\right\} \, d\eta$$

which is equation (1). This will give the nondimensionalized cross-sectional area at station, ξ , for the particular Mach number and θ determining Ω_{TE} .

For convenience in computing, tan Λ_{TE} , tan Λ_{TE} and a can be defined in terms of a reference angle, such as that used in a wing design.

$$\tan \Lambda_{\text{IE}} = \frac{\mu}{A} \left(\frac{\mathbf{x}^{\,t}}{c} \right)_{\text{ref}} \left(\frac{1-\lambda}{1+\lambda} \right) + \tan \Lambda_{\text{ref}}$$
 (9a)

$$\tan \Lambda_{\text{TE}} = \frac{-1}{A} \left[1 - \left(\frac{\mathbf{x}^{t}}{\mathbf{c}} \right)_{\text{ref}} \right] \left(\frac{1 - \lambda}{1 + \lambda} \right) + \tan \Lambda_{\text{ref}}$$
 (9b)

$$a = \left(\frac{x^{t}}{c}\right)_{ref} + \frac{A}{4} \left(\frac{1+\lambda}{1-\lambda}\right) (\tan \Lambda_{ref} - \tan \psi)$$
 (9c)

The tan $\Omega_{\rm LE}$ and tan $\Omega_{\rm TE}$ can also be expressed in terms of a. This may be a convenient form since the limits for η are given, as they were originally derived in reference 9, in these terms:

$$\tan \Omega_{IE} = \frac{\mu(1-\lambda)a}{(1+\lambda)A}$$
 (10a)

$$\tan \Omega_{\text{TE}} = \frac{\frac{1}{1 + (1 - \lambda)(a - 1)}}{(1 + \lambda)A}$$
 (10b)



Application of equation (1).- For certain types of thickness variation, the general equation can be simplified considerably.

Case I: For the most general case, the thickness distribution at the root chord can be different from the thickness distribution at the tip chord. There is <u>linear variation in the physical thickness</u> along a constant-percent-chord line. This means that $f_1(\eta)$ and $f_2(\eta)$ remain variables.

Case II: A simplification in case I is possible when the root and tip sections are the same type but have different ratios of $(t/c)_{max}$, that is,

$$\left(\frac{t_T}{t_O}\right)_{x^*/c} = \gamma$$
, a constant

and

$$\left(\frac{\mathbf{t}_{\tau}}{\mathbf{t}_{\sigma}}\right)_{\mathbf{x}^{\dagger}/\mathbf{c}} \neq \frac{\mathbf{c}_{\tau}}{\mathbf{c}_{\sigma}}$$

therefore

$$f_2(\eta) = \frac{\gamma}{\lambda}$$

For this situation equation (1) reduces to:

$$\frac{S(\xi)}{c_{\sigma}^{2}} = \frac{\left(c_{O}/c_{\sigma}\right)_{\xi} \left(t/c\right)_{\sigma_{max}}}{\tan \Omega_{IE}} \int_{\eta_{1}}^{\eta_{2}} f_{I}(\eta) \left[1-\left(1-\gamma\right) \frac{\eta_{e}^{-\eta}}{\eta_{b/2}}\right] d\eta \tag{11}$$

Case III: A further simplification of case II is possible when the streamwise airfoils at the root and tip are similar, that is, the thickness distribution is the same at the root and the tip.

$$\left(\frac{t_{\tau}}{t_{\sigma}}\right)_{x^{\dagger}/c} = \frac{c_{\tau}}{c_{\sigma}} = \lambda$$

therefore

$$f_2(\eta) = 1$$

The equation for the normalized thickness ratio, (8), becomes:





$$\left[\frac{\mathrm{t}}{\mathrm{c}}\right] = \frac{\mathrm{c}_{\mathrm{o}}}{\mathrm{c}_{\mathrm{o}}} \ \mathrm{f}_{\mathrm{l}}(\eta) \left[1 - (1 - \lambda) \ \frac{\eta_{\mathrm{e}} - \eta}{\eta_{\mathrm{b}/2}} \right] \ \frac{1}{1 + (\eta/\mathrm{a})}$$

and from equations (3), (5), and (10)

$$\left[1-(1-\lambda)\frac{\eta_{e}^{-\eta}}{\eta_{b/2}}\right] = \frac{c_{o}}{c_{o}}\left(1+\frac{\eta}{a}\right)$$

therefore

$$\left[\frac{\mathsf{t}}{\mathsf{c}}\right] = \mathsf{f}_{\mathsf{l}}(\eta)$$

Equation (1) reduces to (see eqs. (2) and (5)):

$$\frac{S(\xi)}{c_{\sigma}^{2}} = \frac{(t/c)_{\sigma_{\max}}(c_{o}/c_{\sigma})_{\xi}^{2}}{\tan \Omega_{IE}} \int_{\eta_{1}}^{\eta_{2}} f_{1}(\eta) \left(1 + \frac{\eta}{\epsilon}\right) d\eta$$
 (12)

With only a slight alteration in equation (1), a different type of wing can be handled, a wing with <u>linear variation in thickness-chord ratio</u> which may be called case IV. For this wing, the ratio of thickness to chord (rather than the thickness itself) will be linear. The equation for ratio of thickness to chord may be defined as:

$$\frac{\mathbf{t}}{\mathbf{c}} = \left(\frac{\mathbf{t}}{\mathbf{c}}\right)_{\sigma} - \left[\left(\frac{\mathbf{t}}{\mathbf{c}}\right)_{\sigma} - \left(\frac{\mathbf{t}}{\mathbf{c}}\right)_{\tau}\right] \frac{\eta_{\mathbf{e}} - \eta}{\eta_{\mathbf{b}/2}}$$

and the normalized thickness ratio (eq. (8)) becomes:

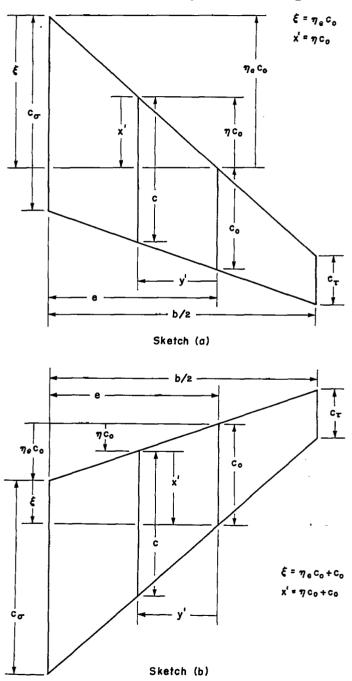
$$\begin{bmatrix} \frac{t}{c} \end{bmatrix} = \begin{bmatrix} \frac{t}{c} \end{bmatrix}_{\sigma} - \left\{ \begin{bmatrix} \frac{t}{c} \end{bmatrix}_{\sigma} - \begin{bmatrix} \frac{t}{c} \end{bmatrix}_{T} \right\} \frac{\eta_{e}^{-\eta}}{\eta_{b/2}} = f_{1}(\eta) \left\{ 1 - \left[1 - f_{2}(\eta) \right] \frac{\eta_{e}^{-\eta}}{\eta_{b/2}} \right\}$$

and the equation for the nondimensionalized area becomes:

$$\frac{S(\xi)}{c_{\sigma}^{2}} = \frac{(c_{o}/c_{\sigma})_{\xi}^{2}(t/c)_{\sigma_{max}}}{\tan \Omega_{IE}} \int_{\eta_{1}}^{\eta_{2}} f_{1}(\eta) \left\{ 1 - [1 - f_{2}(\eta)] \frac{\eta_{e} - \eta}{\eta_{b/2}} \right\} \left(1 + \frac{\eta}{a} \right) d\eta$$
(13)



In general, equations for the streamwise shapes of the wing at the root and the tip will not be available; if plots of these shapes, $[t/c]_{\sigma} = f_1(\eta) \text{ and } [t/c]_{\tau} = [t/c]_{\sigma} f_2(\eta), \text{ are given, approximate or mechanical integrating methods can be used. However, if the streamwise shapes at the root and tip are expressible in equation form as functions of <math display="inline">\eta$, the area can be found by direct integration.



For variations in wing plan form, the primary change in form of the equation will be in the limits of integration. Two symbols take on a different meaning for wings with certain sweeps. For area cuts intersecting a sweptback leading edge (extended if necessary), t and x' are measured in the x direction from the leading edge to the intersection of the leading edge with co (sketch (a)). For area cuts intersecting a sweptforward trailing edge, & and x' are measured in the x direction from the leading edge to the intersection of the trailing edge with c_{O} (sketch (b)). Note that for the sweptforward leading edge, n becomes negative. In both of the above cases, the leading and trailing edges are considered as extending to their point of intersection in order to define the limits of integration for some of the area cuts. For the cuts where this is necessary co will lie beyond the wing tip. Thus the following two sets of equations are needed: one for the sweptback leading edge (set 1) and another for the sweptforward trailing edge (set 2). Set 2 can be obtained from set 1 by replacing x' set 1 by $x'-c_0$ and by replacing ξ in set 1 by ξ -c₀, thus obtaining equivalent-meaning values for ηc_{O} and $\eta_{e} c_{O}$ in terms of ξ and x.



$$\frac{\text{SET } 1^1}{\text{(Sweptback leading edge)}} \qquad \frac{\text{SET } 2^1}{\text{(Sweptforward trailing edge)}}$$

$$c_0/c_\sigma = 1 - (\xi/ac_\sigma) \qquad c_0/c_\sigma = [1 - (\xi/ac_\sigma)] \div [1 - (1/a)]$$

$$\eta_e = \frac{\xi/c_\sigma}{1 - (\xi/ac_\sigma)} \qquad \eta_e = \frac{(\xi/c_\sigma) - 1}{1 - (\xi/ac_\sigma)}$$

$$\eta_{b/2} = \frac{[(b/2)/c_\sigma](\tan \Omega_{IE})}{1 - (\xi/ac_\sigma)} \qquad \eta_{b/2} = \frac{[(b/2)/c_\sigma]\tan \Omega_{IE}[1 - (1/a)]}{1 - (\xi/ac_\sigma)}$$

$$\eta_r = \frac{r/c_\sigma(\tan \Omega_{IE})}{1 - (\xi/ac_\sigma)} \qquad \eta_r = \frac{(r/c_\sigma)\tan \Omega_{IE}[1 - (1/a)]}{1 - (\xi/ac_\sigma)}$$

$$\eta_{B} = \eta_e - \eta_r \qquad \eta_{B} = \eta_e - \eta_r$$

$$\eta_{T} = \eta_e - \eta_{b/2} \qquad \text{for } \eta_{b/2} < \eta_e \qquad \eta_{T} = \eta_e - \eta_{b/2} \qquad \text{for } \eta_{b/2} < \eta_e$$

$$= 0 \qquad \text{for } \eta_{b/2} \ge \eta_e \qquad \frac{x^{\dagger}}{c} = \frac{\eta + 1}{1 + (\eta/a)}$$

When the wing cross-sectional area cut coincides with the unswept percent chord line, equation (1) becomes indeterminate. The following two equations, (14) for linear physical thickness and (14a) for linear thickness ratio, can be used for computing the wing cross-sectional area:

$$\frac{S(\xi)}{c_{\sigma}^{2}} = \frac{(t/c)_{\sigma_{\max}}[(b/2)-r]}{2c_{\sigma}} \left(\left\{ \left[\frac{t}{c}\right]_{\sigma} + \lambda \left[\frac{t}{c}\right]_{T} \right\} - \frac{r}{b/2} \left\{ \left[\frac{t}{c}\right]_{\sigma} - \lambda \left[\frac{t}{c}\right]_{T} \right\} \right) \left(\frac{x^{\dagger}}{c} = \frac{\xi}{c_{\sigma}} \right)$$

(14)

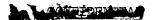
10riginally derived in reference 9.

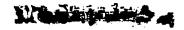
$$\frac{s(\xi)}{c_{\sigma}^{2}} = \frac{(t/c)_{\sigma_{\max}}[(b/2)-r]}{6c_{\sigma}} \left\{ \left[\frac{t}{c} \right]_{\sigma} (2+\lambda) + \left[\frac{t}{c} \right]_{\tau} (2\lambda+1) \right\} - \frac{r}{b/2} \left\{ \left[\frac{t}{c} \right]_{\sigma} (4-\lambda) - \left[\frac{t}{c} \right]_{\tau} (2\lambda+1) \right\} + \frac{2r^{2}}{(b/2)^{2}} \left\{ \left[\frac{t}{c} \right]_{\sigma} (1-\lambda) - \left[\frac{t}{c} \right]_{\tau} (1-\lambda) \right\} \right\} \tag{14a}$$

The following tables of plan forms indicate the differences that occur in the area solution for the various wings. (The quantity a is used as an indicator of the sheared sweep of the leading and trailing edges, $\Omega_{\rm LE}$ and $\Omega_{\rm TE}$, respectively, since it is a function of both of these.)

Equations for Wings of Different Plan Forms

For wings with taper: $0 \le \lambda < 1$										
	For wi	ngs with taper	$0 \le \lambda < 1$							
a	I.E	TE	Equations	Wing shape diagram						
$\infty > a > 1$	Sweptback	Sweptback	Set 1 and eq. (1)							
a = 1	Sweptback	Unswept	Set 1 and eq. (1)							
1 > a > 0	Sweptback	Sweptforward								
	When §/	c _σ < a	Set 1 and eq. (1)	Upper part						
	٤/	c _o = a	Eq. (14)	Dividing line						
	٤/	с _о > а	Set 2 and eq. (1)	Lower part						
a = 0	Unswept	Sweptforward								
	(Indeterminates same as second		: Turn wing over a	nd handle						
0 > a > -∞	Sweptforward	Sweptforward	Set 2 and eq. (1)							





	For wings with no taper:	$\lambda = 1$, $a = \infty$	
Tan $\Omega_{ ext{IE}}$	$\Omega_{ ext{LE}},~\Omega_{ ext{TE}}$	Equations	Wing shape diagram
Tan $\Omega_{ ext{LE}} > 0$	Sweptback	Set 1 and eq. (1)	
Tan $\Omega_{IE} = 0$	Unswept	Eq. (14)	
Tan $\Omega_{ m LE} < 0$	Sweptforward	Set 2 and eq. (1)	

NOTE: The above tables apply for wings with <u>linear physical thickness</u> on a constant-percent-chord line; these tables may also be used for wings with <u>linear thickness ratio</u> on a constant-percent-chord line (see variation in thickness, case IV) if equation (13) is substituted for equation (1) and equation (14a) for equation (14).

Limits of integration (fig. 28(c)) are determined from the geometry of the wing. The limit at the outer edge of a wing will be, η_1 .

$$\eta_{1} = \eta_{T}$$

$$\eta_{T} = 0 \quad \text{when} \quad \eta_{e} \leq \eta_{b/2}$$

$$\eta_{T} = \eta_{e} - \eta_{b/2} \quad \text{when} \quad \eta_{e} > \eta_{b/2}$$

$$(15)$$

Limit at the inner edge of the wing will be, η_2 . For some wing sweeps there will be a maximum value for η which will be called η_{max} (fig. 28(c)).

$$\eta_{\text{max}} = \frac{y'_{\text{max}}}{c_{\text{O}}} \tan \Omega_{\text{LE}}$$

Maximum values for n

λ	$ an~\Omega_{ m IE}$ and $ an~\Omega_{ m TE}$	η _{mex}
< 1	Sweptback	a - 1
< 1 = 1	Sweptforward Sweptback	-1 +1
= 1	Sweptforward All others	- <u>1</u> ∞

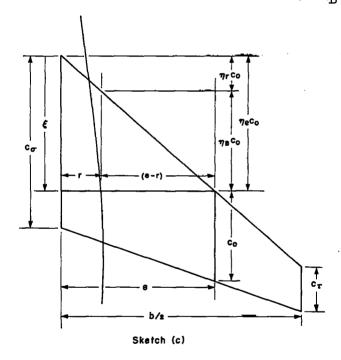


$$\eta_2 = \eta_{\text{max}}$$
 when $\eta_e \ge \eta_{\text{max}}$

$$\eta_2 = \eta_e$$
 when $\eta_e < \eta_{max}$

When there is no maximum value (η_{max} is infinite), $\eta_2 = \eta_e$. For the cross-sectional area of the wings with a body, use η_B in place of η_e . If the cross-sectional area of the wings with an indented body is desired, use η_{B_4} .

For the computation of wing cross-sectional area with a body (with or without indentation) the change in the general equation will be in the limits of integration. For this condition, only the part of the wing outside the body need be considered. This means a limit of integration to correspond with the edge at the body will be needed, 2 $\eta_{\rm R}$.



$$\eta_R c_O = (e-r)(\tan \Omega_{TE})$$

$$\eta_{\rm B} = \frac{\rm e}{\rm c_{\rm O}} \ ({\rm tan} \ \Omega_{\rm LE}) - \frac{\rm r}{\rm c_{\rm O}} \ ({\rm tan} \ \Omega_{\rm LE})$$

$$\eta_{\rm B} = \eta_{\rm e} - \eta_{\rm r} \tag{17}$$

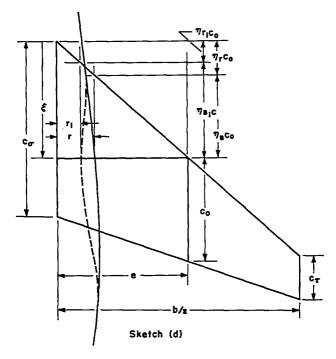
²Since the wing is thin, the curvature at the body in the yz plane will be ignored.



ADDED WING CROSS-SECTIONAL AREA DUE TO INDENTATION; AS(§)

Let $\eta_{B_{\underline{\mathbf{1}}}}$ equal the limits of integration on an indented body.

$$\frac{\Delta S(\xi)}{c_{\sigma}^{2}} = \frac{(c_{o}/c_{\sigma})_{\xi}(t/c)_{\sigma_{max}}}{\tan \Omega_{LE}} \int_{\eta_{B}}^{\eta_{B_{1}}} f_{1}(\eta) \left\{ 1 - \left[1 - \lambda f_{2}(\eta)\right] \frac{\eta_{e} - \eta}{\eta_{b/2}} \right\} d\eta \qquad (18)$$

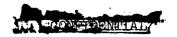


In order to compute $~r_{1}~$ easily an approximation of $~\Delta S(\xi)$ is needed in terms of $~r_{1}$.

$$\frac{\Delta S(\xi)}{c_{\sigma}^{2}} \approx \frac{(c_{o}/c_{\sigma})_{\xi}(t/c)_{\sigma_{max}}}{\tan \Omega_{LE}} f_{1}(\eta) \left\{ 1 - [1 - \lambda f_{2}(\eta)] \frac{\eta_{e} - \eta}{\eta_{b/2}} \right\}_{\eta = \eta_{B}} \left(\eta_{B_{1}} - \eta_{B} \right)$$

$$\eta_{B_{1}} - \eta_{B} = (\eta_{e} - \eta_{r_{1}}) - (\eta_{e} - \eta_{r}) = \eta_{r} - \eta_{r_{1}}$$





$$\frac{\Delta S(\xi)}{c_{\text{G}}^2} \approx \frac{\left(c_{\text{G}}/c_{\text{G}}\right)_{\xi} \left(t/c\right)_{\sigma_{\text{max}}}}{\tan \, \Omega_{\text{IE}}} \, f_{\text{1}}(\eta) \left\{1 - \left[1 - \lambda f_{\text{2}}(\eta)\right] \, \frac{\eta_{\text{e}} - \eta}{\eta_{\text{b/2}}} \right\}_{\eta = \eta_{\text{R}}} \frac{\left(r - r_{\text{1}}\right) \left(\tan \, \Omega_{\text{IE}}\right)}{\left(c_{\text{O}}\right)_{\xi}}$$

$$\Delta S(\xi) \approx c_{\sigma} \left(\frac{t}{c}\right)_{\sigma_{\text{max}}} f_{1}(\eta) \left\{ l - \left[1 - \lambda f_{2}(\eta)\right] \frac{\eta_{e} - \eta}{\eta_{b/2}} \right\}_{\eta = \eta_{B}} (r - r_{1})$$
 (19)

Let

$$G = c_{\sigma} \left(\frac{t}{c}\right)_{\sigma_{\text{mex}}} f_{1}(\eta) \left\{ 1 - \left[1 - \lambda f_{2}(\eta)\right] \frac{\eta_{e} - \eta}{\eta_{b/2}} \right\}_{\eta = \eta_{B}}$$
(20)

$$\Delta S(\xi) \approx G(r-r_{\dagger}) \tag{21}$$

COMPUTATION OF THE RE-INDENTATION

The total cross-sectional area of the exposed wing with the re-indented body is equal to the difference in cross-sectional area between the original body and the re-indented body. Let

 $S_B(\xi,r)$ = cross-sectional area of the original body, at ξ .

 $S_{B_1}(\xi,r_1)$ = cross-sectional area of the re-indented body, at ξ .

 $S_{E}(\xi,r) = cross-sectional$ area of the exposed wing (with the original body) at ξ .

 $S_{E_1}(\xi,r_1) = cross-sectional$ area of the exposed wing (with the re-indented body) at ξ .





The exposed wing cross-sectional area is:

$$\begin{split} \mathbf{S}_{\mathbf{E_{i}}}(\xi,\mathbf{r_{i}}) &= \mathbf{S}_{\mathbf{E}}(\xi,\mathbf{r}) + \Delta \mathbf{S}(\xi) = \mathbf{S}_{\mathbf{B}}(\xi,\mathbf{r}) - \mathbf{S}_{\mathbf{B_{i}}}(\xi,\mathbf{r_{i}}) \\ \\ \mathbf{S}_{\mathbf{E}}(\xi,\mathbf{r}) + \Delta \mathbf{S}(\xi) &\approx \mathbf{S}_{\mathbf{E}}(\xi,\mathbf{r}) + \mathbf{G}(\mathbf{r} - \mathbf{r_{i}}) \end{split}$$

Solve for the unknown r_i ; this is the general approximate formula for re-indentation:

$$S_{E_{i}}(\xi,r_{i})-G_{r_{i}} \approx S_{B}(\xi,r)-S_{E}(\xi,r)-rG$$
 (22)

For a body of revolution at M = 1.0 the cross-sectional area of the body becomes:

$$S_{B}(\xi,r) = \pi r^{2}$$
 $S_{B_{1}}(\xi,r_{1}) = \pi r_{1}^{2}$

Substituting in equation (22):

$$\pi r_i^2 - Gr_i \approx \pi r^2 - S_E(\xi,r) - rG$$

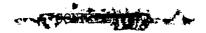
$$r_1 \approx \frac{G \pm \sqrt{G^2 - 4\pi[-\pi r^2 + S_E(\xi,r) + rG]}}{2\pi}$$

when $G \rightarrow 0$; $S_{\mathbb{R}}(\xi,r) \rightarrow 0$; $r_{\mathfrak{s}} \rightarrow r$

$$r_{i} \approx \frac{G}{2\pi} + \sqrt{\frac{G}{2\pi}^{2} + r^{2} - \frac{rG}{\pi} - \frac{S_{E}(\xi, r)}{\pi}}$$
 (23)

Note: When $\frac{\xi^{-C}\sigma}{\tan \Omega_{TE}}$ is greater than r, that is, aft of the trailing-edge juncture, G equals O; hence equation (23) reduces to

$$r_{1} = \sqrt{\frac{\pi r^{2} - S_{E}(\xi, r)}{\pi}}$$
 (24)





An approximation of the re-indentation was made for M = 1.2 (body of revolution) by using in equation (23) the average exposed wing cross-sectional area, $S_{E_A}(\xi,r)$, (i.e., the average of the areas at the various angles of θ for M = 1.2) in place of the exposed wing area, $S_{E}(\xi,r)$. Thus, the re-indentation was made on the plane perpendicular to the x axis and $\Delta S(\xi)$ was evaluated in this plane. For greater accuracy in evaluating the wing areas (S_{E_A} and the final wing areas), the body, as well as the wings, was sheared for each θ angle.





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TABLE I.- COORDINATES OF THE AIRFOIL SECTIONS [All coordinates are referred to the chord of the NACA 64A006 section and are in terms of percent of that chord. Asterisks indicate coordinates that are identical to those of the basic wing. The 64A006 sections are perpendicular to their own quarter chord line, which is swept 39.45°. (Sweep of streamwise quarter chord line is 40.60°.)]

Sections no	ormal to 39.4	o sweep line	<u> </u>	Streamwise sections			
Station	Basic wing (64A006)	Modified wing					
-1.50 -1.25 -1.00 75 25 25 50 725 2.5 5.0 7.0 1.5 20 25 30 35 40 45 50 50 70 75 80 85 90 90 100 100 100 100 100 100 100 100 1	0 .485 .585 .739 1.016 1.399 1.684 1.919 2.283 2.557 2.897 2.995 2.945 2.975 2.945 2.188 2.188 2.188 2.188 2.188 2.188 2.188 2.188 2.189 2.189 2.189 2.189 2.189 2.189 2.189	0 .733 .988 1.173 1.455 1.573 1.675 1.843 1.980 2.211 2.500 2.677 2.800 2.947 3.004 2.995 2.995 2.999 3.000	-2.03 -1.69 -1.35 -1.31 .004 -1.608 -1.340 6.6845 13.621 25.99 36.05 47.32 47.32 47.32 47.35 88.42 57.44 57.42 66.90 71.87 88.42 19.62 19.	0 .464 .559 .705 .965 1.317 1.571 1.775 2.077 2.289 2.428 2.511 2.541 2.520 2.438 2.511 2.520 2.438 2.302 2.132 1.931 1.709 1.468 1.216 .963 .715 .474 .238 .009	0 .705 .948 1.123 1.395 1.505 1.685 1.750 1.893 2.098 2.356 2.585 2.679 2.690 2.637 2.598 2.558 2.558 2.558		
Leading-edge radius	.246	1.190		.167	.810		
Center of leading- edge radius	x = 0.246	x = -0.310		x = 0.167	x = -1.22		





TABLE II.- RADII OF BODIES INDENTED FOR EACH WING FOR DIFFERENT DESIGN MACH NUMBERS, INCHES

			Basic-wir	g hodies	Modified-wing bodies				
Body	Sears-	M = 1.00			M = 1.20	3 65	M = 1.20	M = 1.20	
station	Haack	re-indentation	M = 1.05	M = 1.20	re-indentation	M = 1.05	M = 1.20	re-indentation	
x, in.	body	Le-THOGH PROTOT						-	
10	۹ ٦			-11 %-84-0	. See figure 3	for body si	hape and e	quation.	
+,	`}	Radii the	same for	att poores	. Dee light J	101 0000 -	(a)	(a)	
34.88	ړ ۵۰۰∔		1		4.03 ^a	4.03	4.OL	4.OL	
35.38	4.03	4.03	4.03	4.03ª	4.03 4.04	4.06ª	4.01	4.OL	
36.05	4.06	4.06	4.06	4.04	4.05	4.08	3.99	3.99	
37.05	4.10	4.10	4.10 ⁸	4.05	4.04	4.07	3.93	3.91	
38.39	4.15	4.15 ⁸	4.12	4.04		4.00	3.82	3.78	
40.06	4.21	4.14	4.11	4.00	3.99	3.90	3.70	3.63	
41.73	4.27	4.09	4.08	3.94	3.90	3.78	3.54	3.42	
43.39	4.32	4.00	4.OL	3.81	3.76	3.66	3.41	3.26	
45.06	4.36	3 . 89	3.91	3.68	3.59 3.42	3.52	3.31	3.14	
46.73	4.40	3.76	3.78	3 - 55	3.42		3.23	3.03	
48.40	4.43	3 . 61	3.64	3.44	3.27	3.38 3.26	3.19	2.98	
50.07	4.46	3.45	3.51	3.38	3.18	3.14	3.15	2.93	
51.74	4.48	3.27	3.67	3.33	3.13	3.02	3.12	2.91	
53.41	4.49	3.11	3.24	3.29	3.08	2.93	3.17	2.99	
55.08	4.50	2.98	3.13	3.28	3.10	2.90	3.26	3.12	
56.75	4.50	2.90	3.07	3.38	3.26 3.42	2.95	3.40	3.31	
58.42	4.49	2.86	3.10	3.51	3.42	3.04	3.50	3.44	
60.08	4.48	2.89	3.17	3.60	3.53 3.66	3.17	3.60	3.57	
61.75	4.47	2.97	3.27	3.69	3.74	3.34	3.68	3.66	
63.42	14 - 14 14	3.08	3.42	3.76	3.82	3.54	3.75	3.75	
65.09	4.42	3.26	3.61	3.82	3.86	3.70	3.86	3.80	
66.76	4.38	3.49	3.75	3.86	3.00	3.80	3.84	3.84	
68.43	4.34	3.69	3.85	3.89	3.89	3.86	3.85	3.85	
70.10	4.29	3.85	3.91	3.90	3.90	3.90	3.85	3.85	
71.77	4.24	3.85	3.94	3.89	3.88	3.92	3.85	3.85	
73.44	4.18	4.02	3.95	3.88	3.85	3.93	3.82	3.82	
75.11	4.11	4.06	3.94	3.85	3.81	3.91	3.80	3.80	
76.77	4.04	4.04	3.92	3.81	3.76	3.87	3.74	3.74	
78.44	3.96	3.96	3.88	3.76	3.71	3.83	3.69	3.69	
80.11	3.88	3.88	3.82	3.71	3.65	3.76	3.63	3.63	
81.78	3.79	3.79	3.76	3.65	3.57	3.68	3.56	3.56	
83.45	3.69	3.69	3.68	3.57	3.51	3.60	3.50	3.50	
84.79	3.60	3.60	3.60	3.51	3.48	3.55	3.46	3.46	
85.50	3.55	3.55	3.55	3.48	3.42	3.47	3.40	3.40	
86,63	3.47	3.47	3.47	3.42	3.42	3.39	3.34	3.34	
87.75	3.39	3.39	3.39	3.35	3.26	3.31	3.26	3.26	
88.88	3.31	3.31	3.31	3.26 3.18	3.18	3.22	3.18	3.18	
90.00	3.22	3.22	3.22	3.10	<u></u>			4	

Start of the indentation.

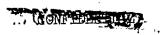




TABLE III.- ZERO-LIFT PRESSURE COEFFICIENTS, $\mathbf{c}_{\mathbf{p}}$

(a) Body pressure coefficients; basic Wing with Sears-Haack body

	M =	0.90	M =	0.95	М =	1.00	M =	1.05	М =	1.10	M =	1.20
θ	Тор	Side	Тор	Side	Top	Side	Top	Side	Top	Side	Top	Side
1-5/cj	00	-900	00	-90°	00.	-900	00.	-90°	00	-90°	00	-900
\$709		-90	0	-90		90	0	-90				-90
-1.295	0.100	0.098	0.110	0.117	0.147	0.145	0.167	0.163	0.164	0.164	0.135	0.135
-1.035		.027		.036		.060		.082		.080		.075
775	003	006	.004	004	.030	.030	.045	.043	.048	.035	.041	.035
5	.000	027	024	030	007 .025	012 .020	003	.009	.01.8	.005	.009	.004
3 2	035	020	035	025	.020	.005	.055	.020	.050	.040	.050	.030
1	080	080	115	105	100	110	045	060	040	- 055	020	045
05		005		010		155		110		100		080
0	065	.240	055	.250	160	.200	110	.215	100	.205	075	.180
.05		003		.010		.025		.020		.055		.055
.1	040	073	020	070	040	055	075	050	060	025	050	.000
.2	020 .030	- 035	010 .050	030 .015	.050	.025 .080	050	090	030 .010	080 025	040	060 055
.3	.050	.035	.065	.050	.115	.100	.090	.075	.100	.090	.080	.065
.5	.010	.010	.020	005	.665	.050	.050	.020	.060	.040	.060	.035
.5	.080	.060	.100	.080	.155	.130	140	.110	145	.135	.120	.095
.7 .8	.010	020	.015	010	.075	.060	.090	.075	.145	.125	.130	.120
.8	080	080	120	120	055	055	O40.	030	.030	.030	.030	.030
.9	090	055	180	165	115	100	100	080	020	010	015	010
.95 1.00	060	020	130	090	755	110	125	060 040	050	025 015		015 015
1.05	000	.030	130	.020	155	075 065	125	060	050	005	050	020
1.1	030	.000	030	.010	125	050	155	075	110	030	090	045
1.2	025	020	015	007	110	100	110	080	090	060	070	015
1.3		020		010		135		070		070		060 [
1.4	020	020	010	010	135	140	090	090	080	080	065	070
1.6	025	025	020	020	005	020	095	080	080	090	055	050
1.8	090	040	050	045	020	005	080	080	095	100	095	095
<u></u>	(ъ)		ressure							ack bod		
3	.035	.035	.020	.010	.075	.010	.030	030	.007	015	007	137
2	.027	055	.01 ¹ 4	.035	.077	.040	.107 .085	.010	.057	020 025	030	110
05		.098 .287	003	.295	.052	.137 .325	.005	.103 .335	.110	.285	.100	.190
0 1	021	.150	045	.162	.005	.190	.040	.247	.065	.270	.082	.283
.05		.000		.000		.024		130		.120		.135
.1	050	045	080	020	041	040	010	.068	.020	.067	.043	.090
.2	075	075	110	090	073	085	045	.000	009	.005	.012	.035
3 4	097	087	133	112	097	103	065	045	026	025	012	.003
•4	118	100 135	162 212	123	115	109 120	090	060	040	040	033	020
.5	135 090	187	212	170 225	150 175	- 175	130 157	103 140	070	055 103	055 075	082
7	055	167	227	255	195	205	170	175	120	130	095	l325 l
.8	047	130	145	273	210	220	16a	205	135	140	114	130
.9	.005	067	050	285	170	230	110	200	107	145	107	127
95		020		172		220		180		140		120
1.00	.025	.037	.007	030	123	195	066	130	066	107	088	105
1.05		.070		.035		167		060		045		040
1.1	.027	.035	.019	.015	065	130	030	090	055	050	043 060	050
1.2	.027	.007	.010	010 026	.050	015 .040	085	132 100	085	072 108		067 080
1.4	.022	.012	.000	030	.040	.047	060	067	055	055	070	065
1.6		.026		.022		106		060		065		055
1.8		.010		007		010		055		068		062
<u></u>									 _			

¹See figure 6 for the definition of the notation.





TABLE III.- ZERO-LIFT PRESSURE COEFFICIENTS, $\mathbf{C}_{\mathbf{p}}$ - Continued

(c) Body pressure coefficients; basic wing with M = 1.05 indented body

	(c) Body pressure coefficients; basic wing with M = 1.05 indented body											
	M =	0.90	M =	0.95	M =	1.00	M =	1.05	M =	1.10	M =	1.20
6	Top	Side	Top	Side	Top	Side	Top	Side	Top	Side	Top	Side
· ·	00	-90°	00	-90°	00	-90°	00	-90°	00	-90°	00	-90°
£'/cj	0-	-90	0.	-90	0-	-90	0,	-90	U-	-90	0-	-90
-1.295	0,100	0.098	0.110	0.117	0.147	0.145	0.167	0.163	0.164	0.164	0.135	0.135
-1.035		.027		.036		.060		.082		.080		.075
775	003	006	.004	004	.030	.030	.045	.043	.048	.035	.041	.035
5	012	027	024	030	007	012	003	.009	.018	.005	.009	.004
3	015	010	030	030	015	030	015	.000	.010	.020	005	.020
2	035	030	045	035	005	015	.000	.010	.020	.020	.000	.000
1_	060	045	075	065	050	055	035	025	015	020	025	020
05		025		050		100		080		070		040
0 05	095	.220	110	.220	185	.195	150	.210	120	.200	110	.175
.05	705	.000	71.5	.000		.010	7.00	.057		.080		.065
.1	125	070 145	145 170	080	155	050 120	130	030 120	070	.010	095	010
'-	130 100	125	,	170	125		125		065 065	085	080	095
•3 •4	050	100	105 085	135 115	095 065	136 115	125 110	135 125	055	095 075	075 070	110
'	025	060	060	090	025	070	090	090	025	035	045	070
.5	.045	.000	.025	005	.030	.000	020	040	.035	.015	010	030
.7	.085	055	.075	.040	.090	.055	.065	.030	.110	.080	.070	.040
.8	.085	.070	.070	.055	.095	.070	.080	.660	145	.120	.100	.080
.9	.070	.060	.060	.035	.090	.065	.080	055	150	.130	.110	.095
95		.045		.010		.045		.048		.120		.090
1.00	015	.020	040	030	.020	.025	.000	.040	.070	.100	.080	.080
1.05		015		060		010		.010		.050		.055
1.1	065	~.050	085	080	055	055	100	065	040	015	040	.000
1.2	095	:080	110	090	170	110	140	095	100	060	085	045
1.3		080		090		155		~.110		090		070
1.4	075	077	080	080	175	155	150	120	120	110	085	080
1.6	060	060	075	075	080	080	140	117	125	120	090	085
1.8	040	040	050	050	025	025	170	~.090	105	100	110	090
1	(d) Bod	y press	ure coe	fficien	ts; mod	ified w	ing wit	h M=	1.05 ir	dented	роду	
3	060	065	065	055	030	025	050	040	020	020	020	020
2	070	050	050	040	010	.010	020	025	020	005	010	010
1	115	020	115	015	060	.010	050	030	050	035	045	050
05		.010		.020		.000		060		115		110
0	170	.175	160	.195	150	.235	200	.210	175	.180	155	.160
.05		- 205		180		095		090		090		055
.1	160	225	175	220	110	250	140	190	115	160	090	145
.2	130	175	155	200	095	260	125	185	090	200	065	205
•3 •4	100	120	120	135	090	140	125	170	100	125	085	135
• 4	070	080	085	080	080	100	120	135	095	100	100	105
•5 •6	045	055	040	050	040	050	095	100	075	080	075	085
.5	.010	.000	.030	.000	.050	.010	030	045	025	040	010	050
.7	.090	.040	.100	.050	.120	.075	.100	.030	.070	.050	.090	.040
8.	.100	.045	.105	.050	.125	.095	.145	055	.095	.090	.130	.065
•9	.075	.040	.070	.035	.100	.085	.140	.057	.080	.100	.125	.070
1.00	020	025	.005	010 030	.055	.050	.100	.020	.040	.090	.095	.065
1.05	020	040		040		005		015	.040	.005	.05)	.035
1.1	060	050	045	050	025	030	.000	030	040	030	.010	.025
1.2	080	065	085	055	100	075	080	060	105	070	060	020
1.3		070		065		110		090		110		060
1.4	087	070	100	070	140	105	130	110	140	120	085	075
1.6	080	060	090	060	045	035	130	110	130	100	095	090
1.8	030	030	030	030	.010	.010	080	075	080	065	095	075
L									<u></u>			



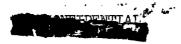


TABLE III.- ZERO-LIFT PRESSURE COEFFICIENTS, $\mathbf{C}_{\mathbf{p}}$ - Continued

(e) Body pressure coefficients; basic wing with $\,\mathrm{M}=1.20\,$ indented body

	M = 0.90		M = 0.95		M = 1.00		M = 1.05		M = 1.10		M =	1.20
θ	COT	Side	Top	Side	Тор	Side	Top	Siđe	Top	Side	Top	Side
5'/cj	00	-900	00	-900	00	-900	00	-900	00	-90°	00	-90°
		<u> </u>	0.770						0.1()		0 305	
-1.295	0.100	0.098	0.110	0.117	0.147	0.145	0.167	0.163	0.164	0.164	0.135	0.135
-1.035		.027		.036		.060		.082		.080		.075
775	003	006	.004	004	.030	.030	.045	.043	.048	.035	.041	.035
5	012	027	024	030	007	012	003	.009	.018	.005	.009	.004
3	055	036	044	042	030	024	010	008	007	015	009	015
2	016	038	010	042	.010	004	.019	017	.015	021	.005	023
1	040	003	023	.000	.017	.046	- 020	020	012	027	017	032
05		.037		.061		.099	[[']	.000		031		030
0	005	.258	020	.274	.062	.319	007	287	027	.260	026	.215
.05		.085		.100		.150		.150		.150		.125
.1	016	.016	.005	.037	.056	.090	.055	.092	.051	.097	020	.082
.2	037	064	010	050	.035	.020	.042	01/14	179	045	.050	.036
1 .3]	081	105	057	090	010	030	.007	.005	.040	.017	.030	.010
4	102	150	083	133	027	070	012	047	.025	006	.013	015
5	134	196	123	183	068	110	058	090	010	031	015	041
.3 .4 .5	160	236	153	226	100	160	075	125	027	096	022	067
.7	191	255	197	256	149	197	- 120	170	042	118	055	103
.7	147	176	230	273	181	218	150	185	083	123	088	115
9	- 091	110	223	276	176	236	142	185	085	125	082	- 123
.95		058		240		227		183		123		125
1.00	048	.005		110	203	150	120	137	123	100	117	- 115
1.05		.027		016		100		072		055		050
1.1		.004	223	.001		116		100		090		077
1.2	058	007	027	.024	210	116	137	090	191	051	134	067
1.3	.0,0	014		034		107		065		045		058
1.4	o48	018	019	.017	127	106	075	060	102	050	085	055
1.6	- 048	022	031	003	.013	.017	095	071	107	094	083	062
1.8	049	027	042	030	.024	.019	076	078	083	083	092	070
 			ure coe							dented		
3	030	020	045	030	025	.000	010	.010	005	.020	.005	.020
2	170	020	220	030	140	.010	090	.020	075	.025	055	.020
1	110	.000	080	010	290	065	235	100	205	110	170	055
05		.020	,	.010	~	155		160		170		135
0	070	.240	095	.250	030	.175	045	.215	080	.210	130	.160
.05		060		020		.000		.010		.030		.040
.1	025	200	035	207	.035	155	010	160	020	140	055	085
.2	.000	050	.005	055	.070	.020	.005	090	.025	105	.005	100
.3	.020	.000	.030	.000	.090	.065	.030	.005	.060	.015	.041	.000
1 .4]	.025	.020	.055	.025	.105	.095	.075	.060	.090	.075	.070	.055
.5	.020	.040	.055	.042	.110	.115	.095	.085	.120	.105	.095	.090
.6	.010	.050	.015	.040	.080	.105	.080	.090	.120	.115	.110	.110
.7	080	010	140	015	060	.050	045	.060	.020	.090	.025	.110
.8	075	110	185	180	122	195	110	070	045	015	030	010
.9	070	080	205	190	160	125	150	115	085	045	070	045
-95		055		180		140		115		050		055
1.00	.035	010	120	120	170	095	140	100	090	060	080	060
1.05		.035		030		020		030		.000		.000
1.1	.185	.005	.200	040	160	070	105	085	080	055	050	030
1.2	.185	040	.200	045	180	150	120	100	120	085	105	070
1.3		030		030		155		095		087		070
1.4	025	025	045	040	005	025	095	080	100	070	090	070
1.6	045	030	070	060	.000	OlO	035	045	085	060	060	070
1.8	035	025	030	.030	.070	145	.035	100	065	075	040	060





TABLE III.- ZERO-LIFT PRESSURE COEFFICIENTS, $\mathbf{C}_{\mathbf{p}}$ - Concluded

				(g) Wing pressure coefficients; basi														
~ -	и=0.90			M=0.95		M=1.00		N=1.05			M=1,10			N=1.20				
x'/c	0.18	0.51	0.89	0.18	0.51	0.89	0.18	0.51	0.89	0.18	0.51	0.89	0.18	0.51	0.89	0.18	0.51	0.89
0.000	0.570	0.495	0.490	0.600	0.510	0.490	0.625	0.540	0.520	0.635	0.560	0.550	0.650	0.600	0.580	0.660	0.610	0.495
.0125	015	080		.320	078		.061	011		.110	001		.065	.031	==	.090	.005	
.05	027	109	175	.030	102	169	.060	041	132	.058	030	091	.056	.015	062	.046	012	021
.10	055	143	205	024	129	223	.025	~.075	165	011	057 084	112	.039	013	068	.018	031	042
.20	100 140	189	240	071	161 200	291 339	022	120 161	219 268	- 045	120	- 151 - 203	-:011	0\8 077	103	013	070	067
,¥0	174	251	215	150	250	371	109	202	314	084	162	265	~.045	113	220	0-9	100	147
.50 .60	215 266	267 228	180 130	200 250	303 345	400 421	151	240 275	358	125 171	212	311 340	088	162 193	270 308	060	140	197
.70	- 270	15	070	- 290	349	- 006	233	300	439	- 205	259	400	142	204	326	141	190	270
.80	180	073	000	302	- 250	.077	255	308	449	211	260	377	155 147	203	325	155 148	187	276
.90	099									100 Sears-E		-,180		148	175			
.000		498	-535		.490	.507		.520	.515		.520	.570	T	.570	.578		.600	.605
.0125	015		122	.009		:2	.062			.060		-2	.052			.160		
.05	- 137	285	- 435	125 135	315 317	532	070 082	295	495	070	295	397	- 042	225 263	385	.015 015	125	220
1.16	158	-,235	- 332	127	- 270	410	075	212	- 378	075	212	355	040	-,190	340	010	155	225
.20	133	180	248	117	210	337	072	165	- 27	030	165	250	025	- 105	210	007	090	260
.40	110 120	160 167	209 131	112	197 217	318 355	060	150 163	248	040	150 165	- 205	025	077 085	152 167	020	060	110
] .50]	157	170	112	160	250	287	-,122	200	310	100	200	255	075	125	222	040	o3o	245
.60	180	142 105	085	210	287	065	170	240	340 368	145 182	235 260	295	110	163	255	065	115	205
.80	130	040	035	285	295 140	.052	242	255	- 350	207	254	305	135 150	175 190	293	135	135 145	230
.90	065	.035	.095	230	.045	.115	227	203	200	190	205	.150	140	170	.220	125	125	.290
				(1) W			coffici			ng with	K = 1		ented b					
.000	115	.510	495	105	.525	.515	075	.525	.540	075	.530	.500	040	-555	-545	035	.600	-595
.025	140	045	l i	155	045		140	075		130	035		105	.015	,	100	.000	
.05	120	075	140	165	065	125	135	085	180	135	040	090	090	020	050	120	035	075
.10	115	090 120	155	115	095 120	145 195	125 125	095	175	120	095	115 157	075	055	065	100	080	078
i .30	045	135	205	- 055	145	275	045	145	240	125	160	210	045	118	155	065	120	145
.¥0 .50	015	145 150	195 160	015	155	- 330	.000	160 160	275	035	195	280 315	.025	137 150	215	037	135 165	195 235
.60	.020	135	- 125	.005	160	305 125	.030	140	310	.025	185	340	.035	130	305	.055	185	275
.70	.015	100	075	003	130	- 035	.030	115	350	.025	140	- 345	.085	095	315	.055	160	295
.80	.007	050	015	020	075	.035	.020	125	030	.020	085	200	.070	- 050	240	.025	- 100	290 350
 .,,,			10,0			_	efficie						ndented		1447		12	
.000		.510	.485		525	.515		-535	-525		.530	-535		.560	.560		.600	.600
[.0125]	075			045			015			.000			-0+0			.085	· i	
.025	245 275	215 215	- 3-5	220	220 235	345	190 245	290	400	175 235	300 345	420	145 215	235 375	410	090	230	350
.10	235	180	315	240	190	290	210	235	340	215	300	- 395	210	320	415	180	330	390
.20	140 080	135 115	230	160	135 110	- 240 - 245	155 110	155	240	165 125	215 170	295	170	195	275	175	235	365
1.50	055	110	140	050	100	270	090	095	215	6	145	240	080	110	200	- 055	075	220
.50	045	115	115	035	115	160	080	095	242	100	150	255	080	125	220	J055	100	205
.60 .70	025	115 095	100	015	125	095 035	025	100	260	050	- 120	265 250	050	120	245 235	075	180	200
.80	035	055	007	025	050	.020	.015	080	015	030	085	180	.015	055	215	015	095	225
.90	035	.005	.060	025	.000	.100	.015	010	160	015	0+5	.280	.035	025	.260	.025	015	.345
.000		27.2	200	(E) W			oeffici			ng with	.540		ented b		260		.600	E78
.025	080	.313	.490	080	.550	495	.006	.565	.500	55		.530	060	-570	.560	050		-575
.025	050	018		050	005		- 025	.060		120 ·	015		110	~.01.5	_	090	.020	
.05	028	~.035 ~.060	140 155	040	020	135 155	045	.010	045 085	050	030	050	- 055	035	025	075	015	035 055
.20	050	065	195	030	070	195	.005	~.030	135	010	060	- 105	.040	015	075	005	090	085
.40	035	116 - 185	215	030	105	270	.000	050 080	185	.010	090	140 185	.060	030	110	.060	095	120 150
50	085 105	145 165	175 150	095 155	145 195	325 345	025	140	300	015 085	100	235	- 010	060	160	015	090	185
.50 .60	050	~.150	132	165	215	120	135	~.155	350	120	120	297	050	~.065	- 250	040	105	210
.70	020	105 045	110	080	230 115	.015	122	185 190	425	098	155 165	350 315	031	095	275	.012	070	245 240
:00	050	.025	.100	100	.0-6	.150		~.120	195		125	.260	014	095	.317	.000	070	.400
											1.20 1	ndented						
.000		-535	.525		.540	.515	===	.580	.540		.550	-555	==	.580	-575		.600	-595
.0125	065 250	250		045	255		020	175		010	275		.020 160	310		115	220	l <u></u> l
.05	270	240	+35	260	- 250	445	2 \ 5	180	340	- 260	- 295	395	225	370	370	200	325	345 365
.10	165	185	320	200	195	395	175	~.140	265	230	205	i 320	200	225	307	200	310	365
.20	090	130 105	250 190	085	143 120	300 285	020	087 060	210	040	180	210 165	135 030	090	180 110	050	230	335 260
.40	015	110	110	025	~.105	340	.030]065	245	005	078	200	.020	037	140	.015	060	150
.50 .60	025 045	130 130	100	030	125	320 165	025	100	290	000	080	240 265	.010	045	175 210	.025	075	160 180
.70	080	-,110	055	035 085	250 ·	010	030	190	315 320	020	155	280	.040	100	230	040	090	-,190
.80	110	055	000	185	185	.0-2	130	190	280	115	175	290	055	125	235	050	095	200
.90	070	.020	.065	190	015	.105	135	130	.150	120	145	.215	065	115	,275		100	.365





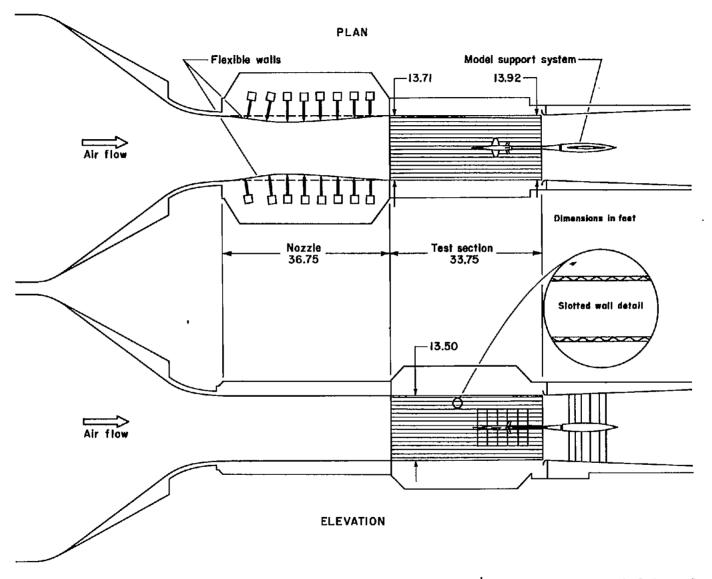


Figure 1.- Two views of the high-speed region of the Ames 14-foot transonic wind tunnel.

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Figure 2.- Rear view of test section and model support system of the Ames 14-foot transonic wind tunnel.



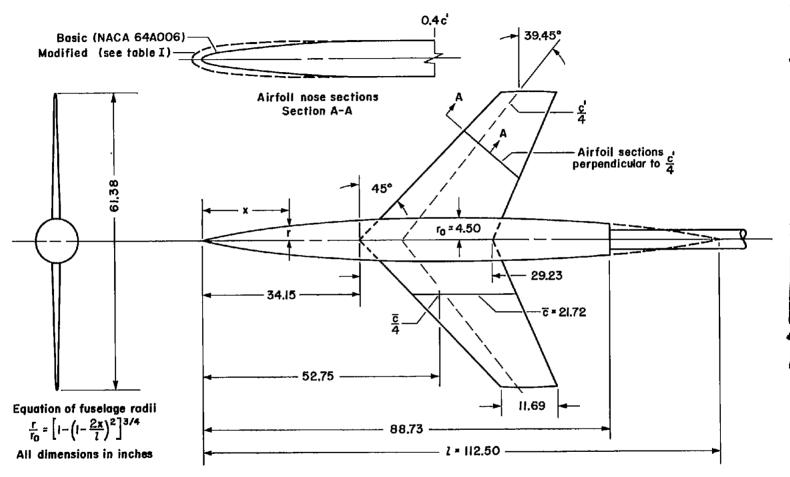
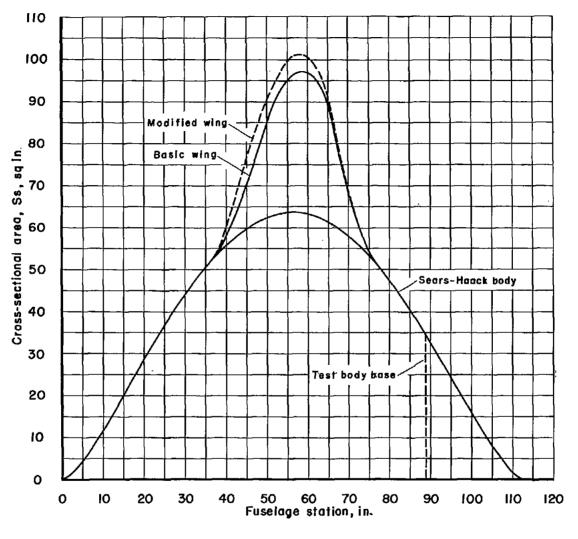
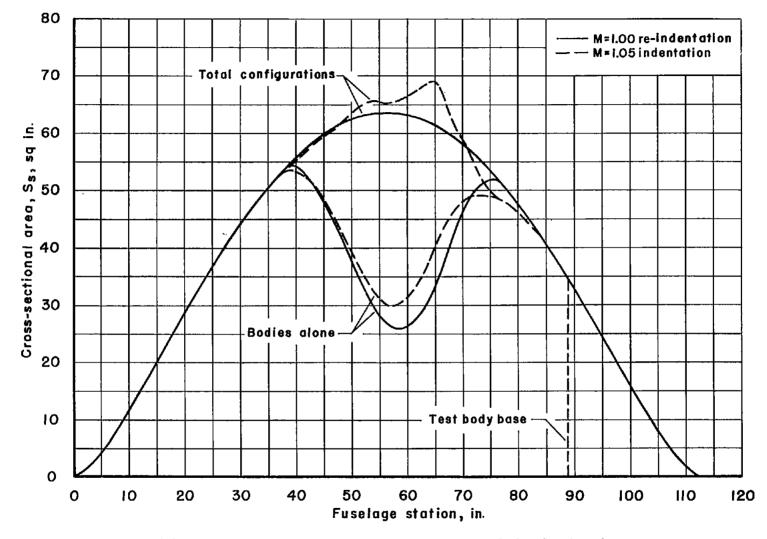


Figure 3.- Two-view drawing of the basic aspect-ratio-3 wing with the fineness-ratio-12.5 Sears-Haack body, and sketch of the modified wing section.



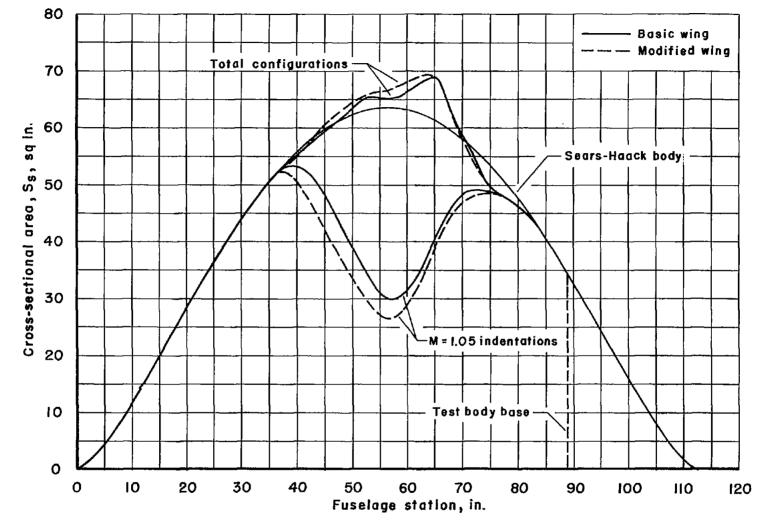
(a) Sears-Haack body; basic and modified wings.

Figure 4.- Cross-sectional area distributions for the bodies and wing-body combinations (M = 1.00).



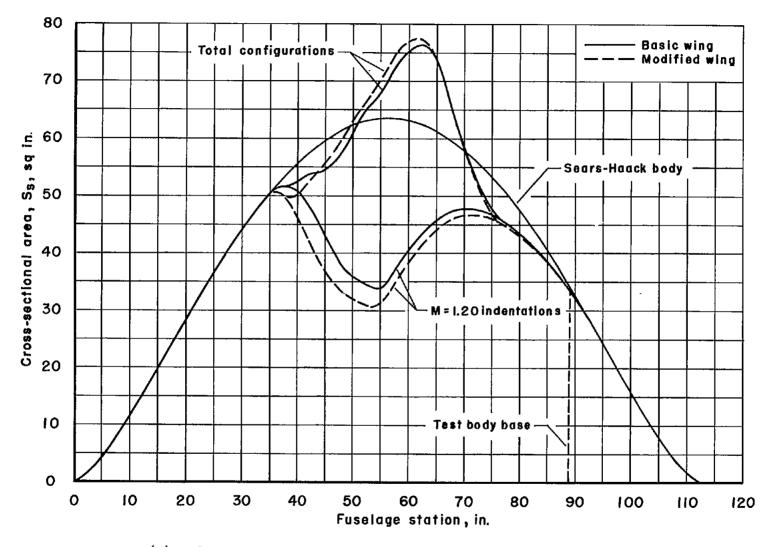
(b) Body indentations for M = 1.00 and M = 1.05, basic wing.

Figure 4.- Continued.



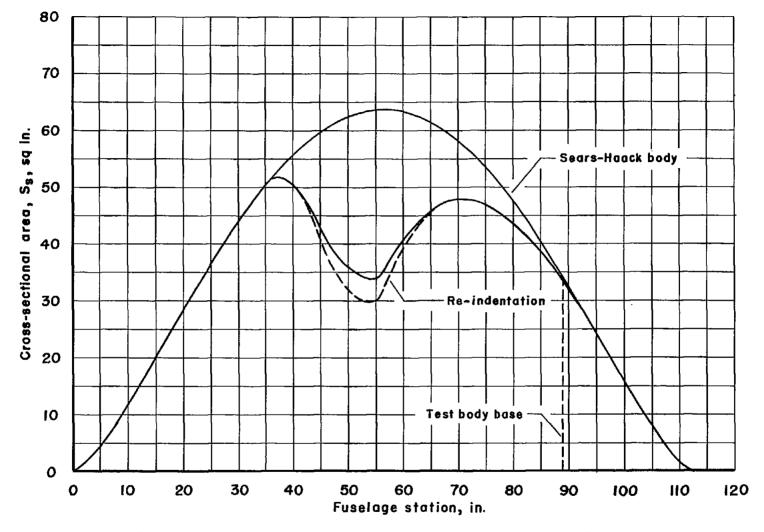
(c) Body indentations for M = 1.05, basic and modified wings.

Figure 4.- Continued.



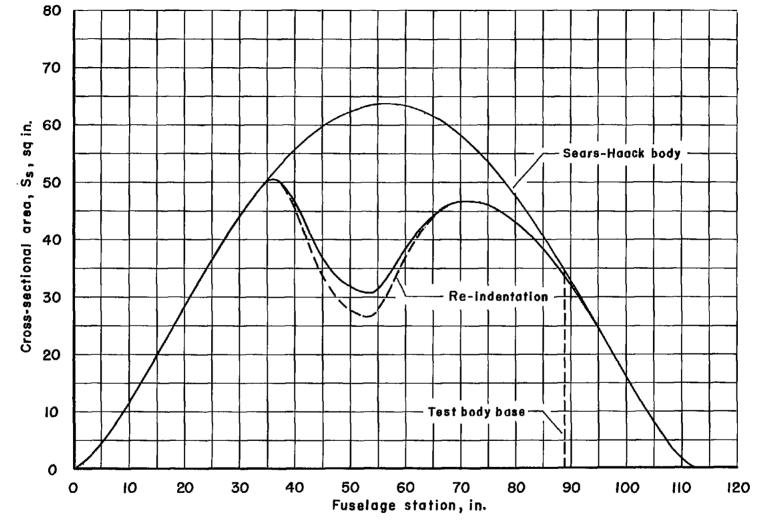
(d) Body indentations for M = 1.20, basic and modified wings.

Figure 4.- Continued.



(e) Body indentation and re-indentation for M = 1.20, basic wing.

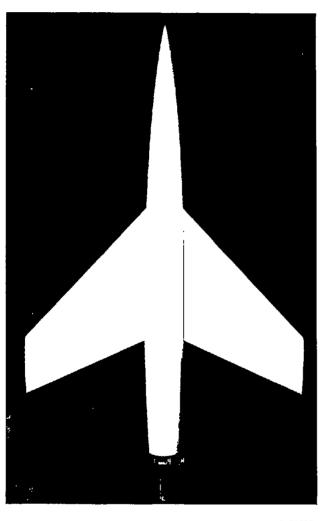
Figure 4.- Continued.



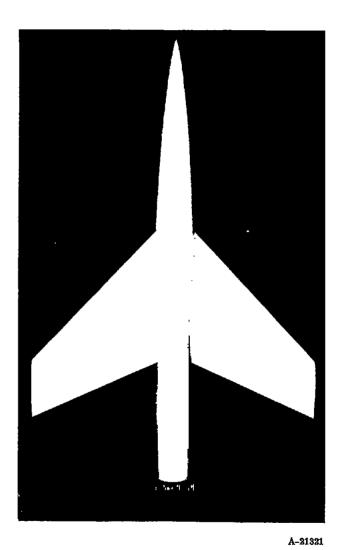
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(f) Body indentation and re-indentation for M = 1.20, modified wing.

Figure 4.- Concluded.



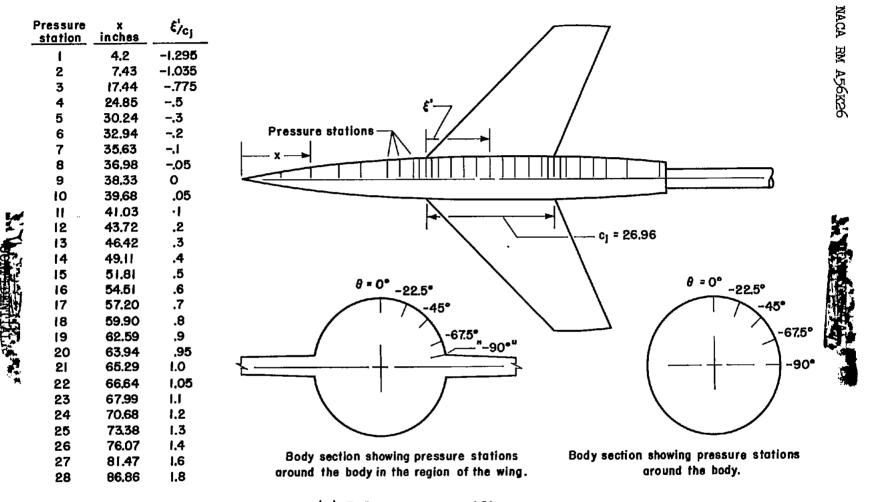
(a) The modified wing with Sears-Haack body.



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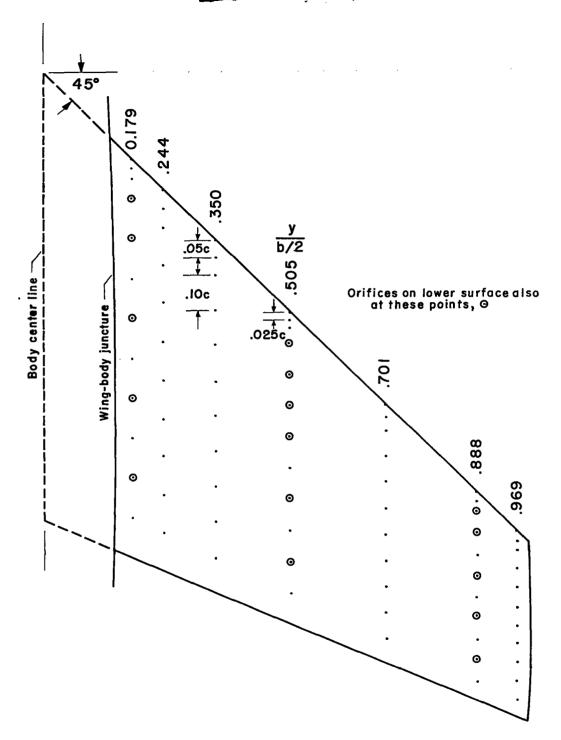
(b) The basic wing with M = 1.20 re-indented body.

Figure 5.- Representative photographs of the models.



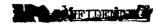
(a) Body pressure orifices.

Figure 6.- Location of pressure orifices on all models.



(b) Wing pressure orifices.

Figure 6.- Concluded.



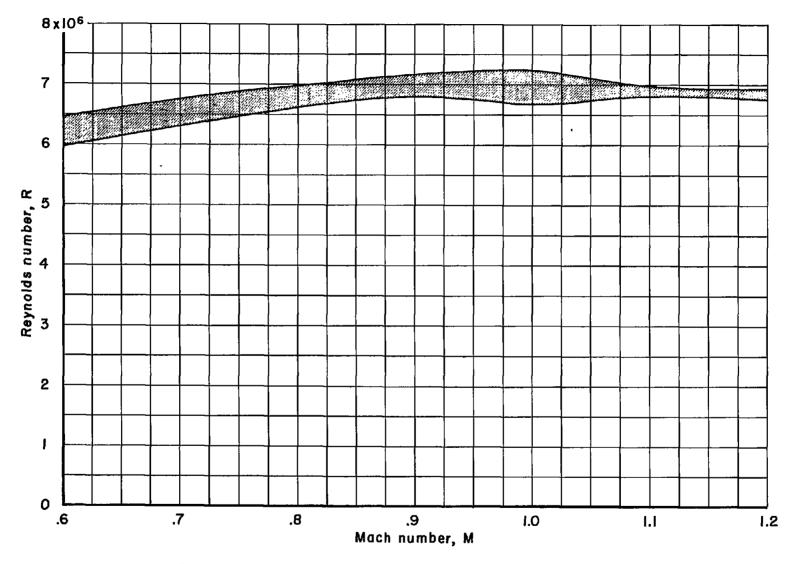


Figure 7.- Reynolds number variation for the tests based on the mean aerodynamic chord of the basic wing.

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O Basic wing - Modified wing

M = 0.60

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.6

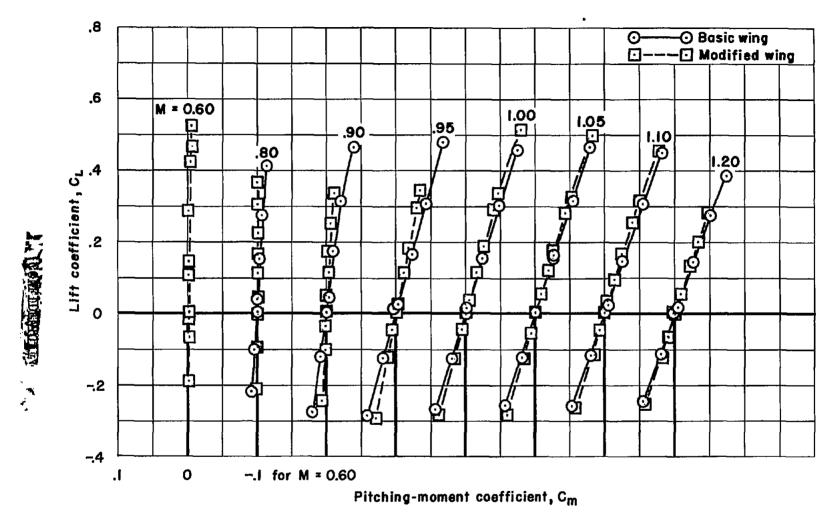
0

(a) C_L vs. α; Sears-Haack body.

Angle of attack, α , deg

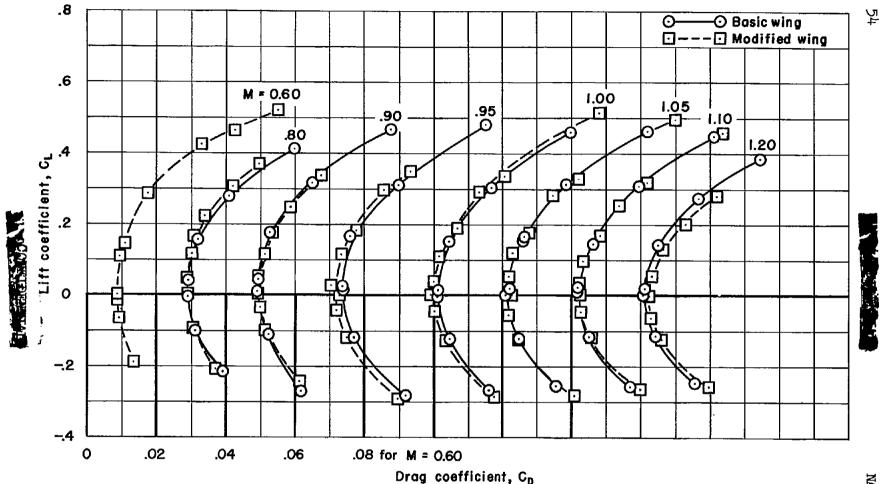
12 for M = 0.60

Figure 8.- Aerodynamic characteristics of the basic- and modified-wing models with the Sears-Haack body.



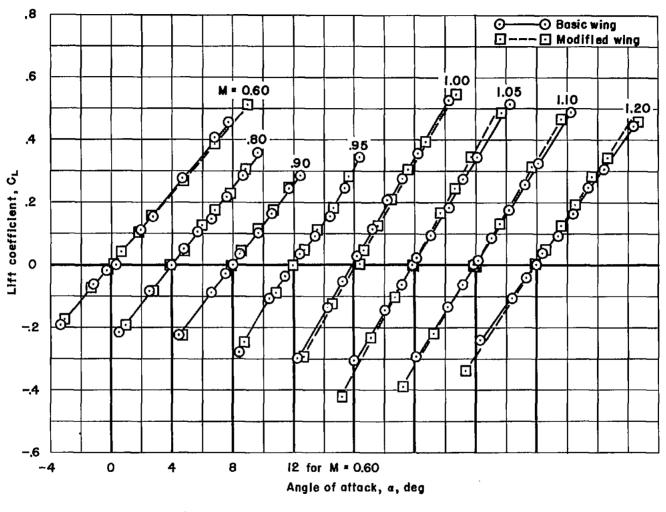
(b) C_L vs. C_m ; Sears-Haack body. Figure 8.- Continued.





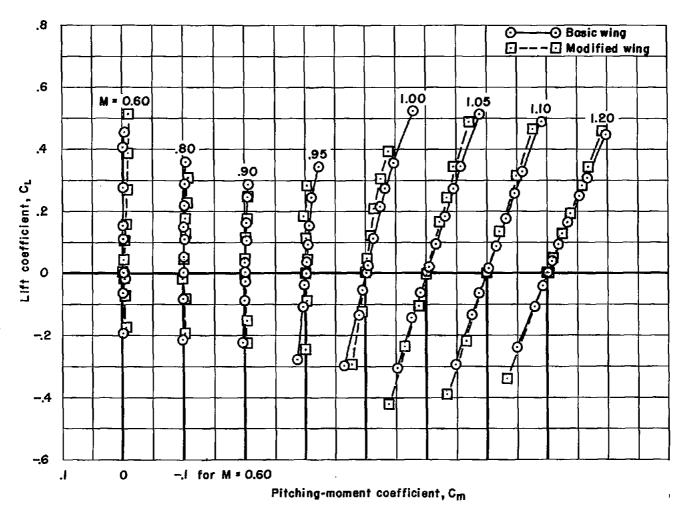
(c) C_{L} vs. C_{D} ; Sears-Haack body.

Figure 8.- Concluded.



(a) C_L vs. α ; M = 1.05 body indentations.

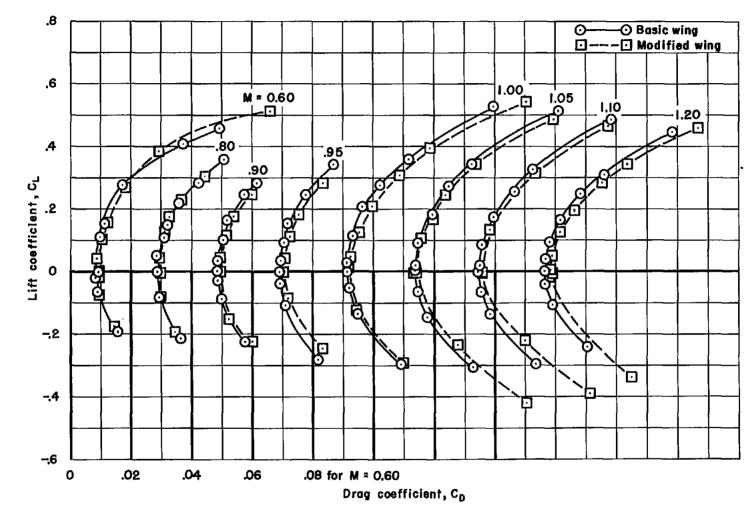
Figure 9.- Aerodynamic characteristics of the basic- and modified-wing models with bodies indented for M = 1.05.



(b) C_L vs. C_m ; M = 1.05 body indentations.

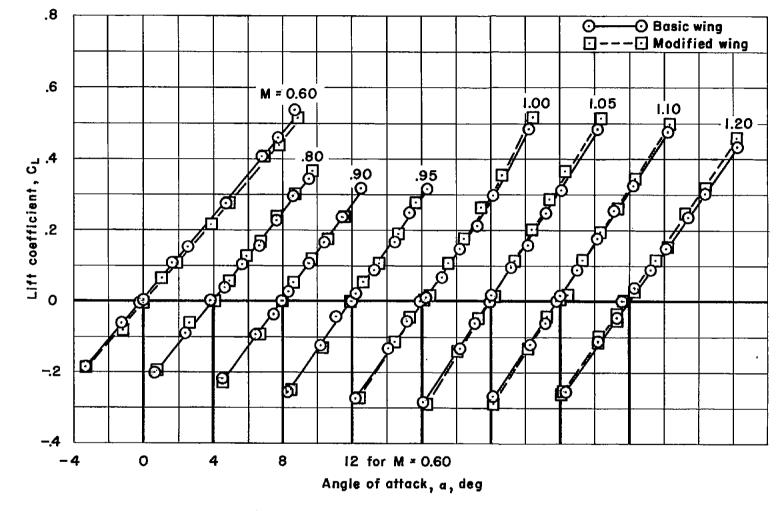
Figure 9.- Continued.





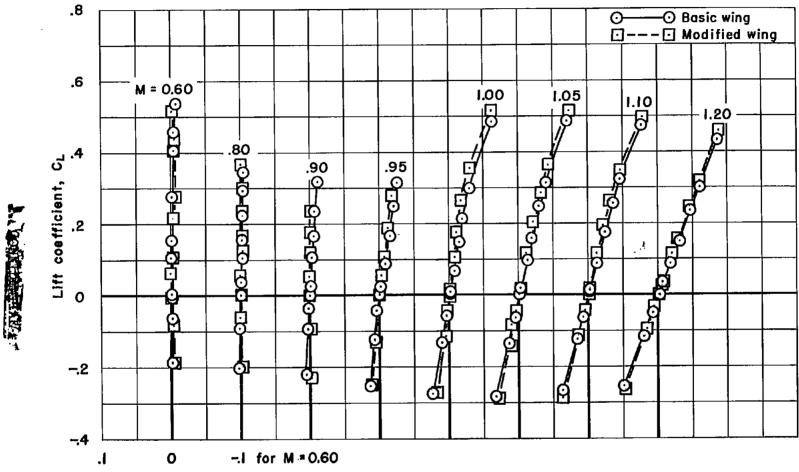
(c) C_L vs. C_D ; M = 1.05 body indentations.

Figure 9.- Concluded.



(a) C_L vs. α ; M = 1.20 body indentations.

Figure 10.- Aerodynamic characteristics of the basic- and modified-wing models with bodies indented for M = 1.20.



Pitching-moment coefficient, Cm

(b) C_{T_i} vs. C_{m} ; M = 1.20 body indentations.

Figure 10.- Continued.

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(c) C_L vs. C_D ; M = 1.20 body indentations.

Figure 10.- Concluded.

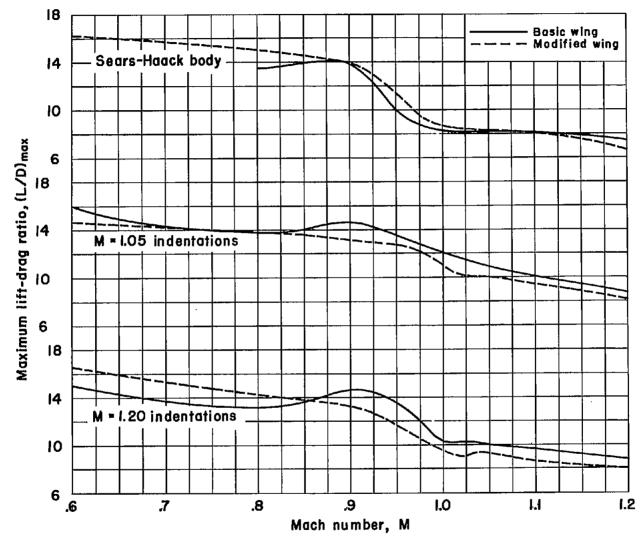


Figure 11.- Maximum lift-drag ratios for the basic- and modified-wing models with various bodies.

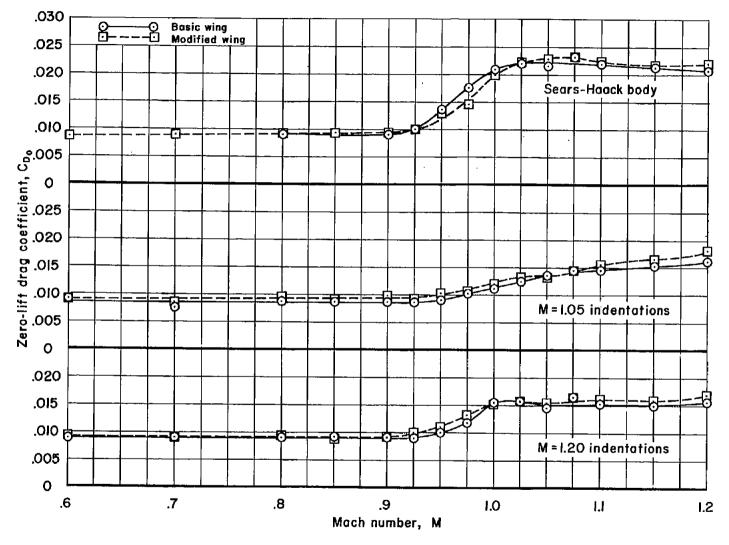


Figure 12.- Zero-lift drag coefficients for the basic- and modified-wing models with various bodies.

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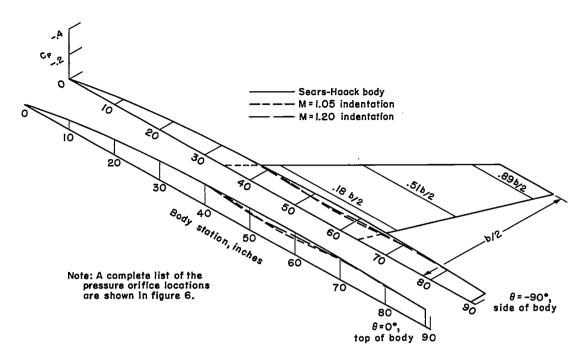


Figure 13.- Regions of wing and body represented by the pressure curves of figure 1^{1} .

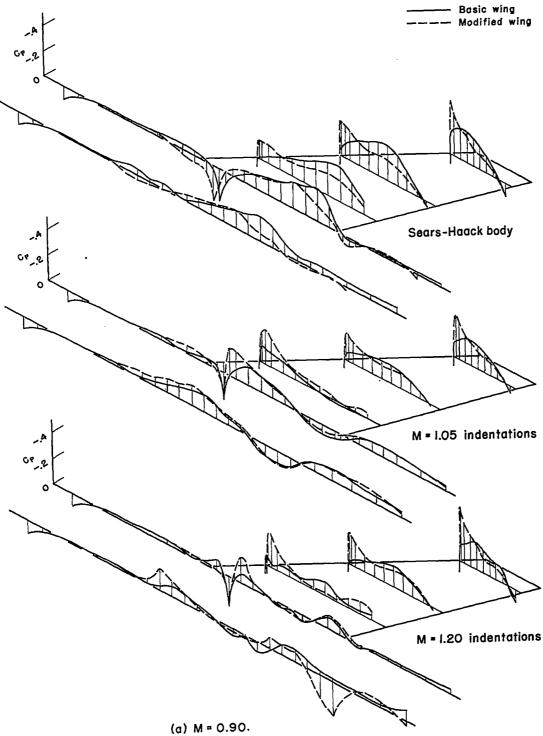


Figure 14.- Representative zero-lift pressure distributions.



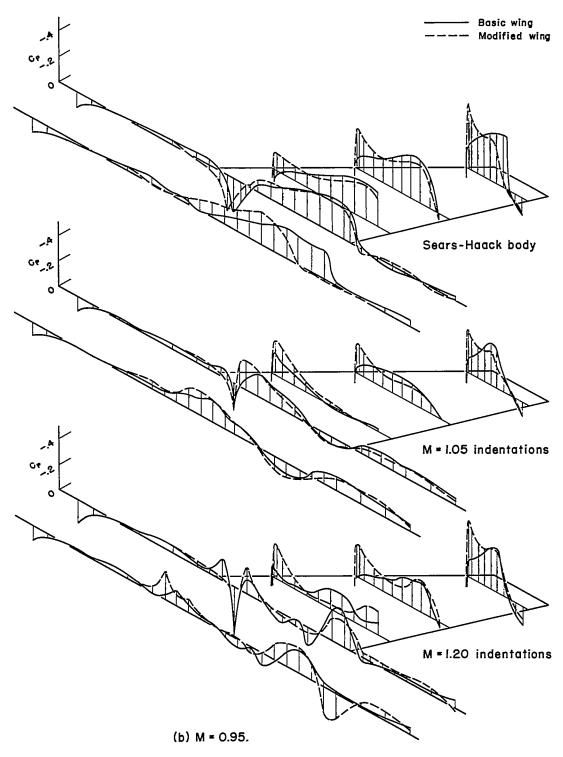
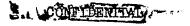


Figure 14.- Continued.





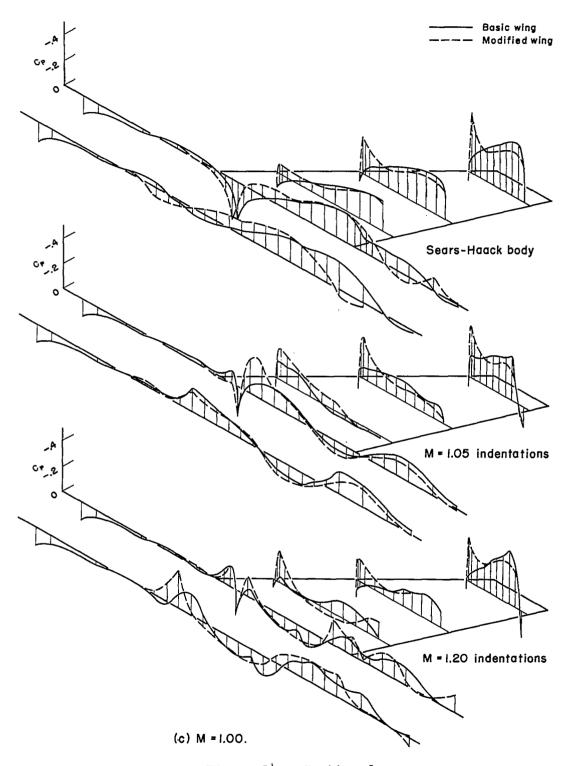


Figure 14.- Continued.



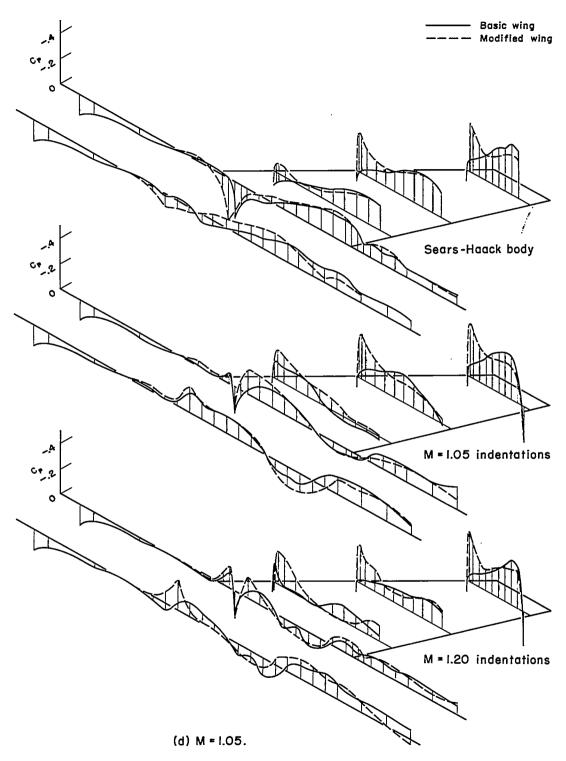


Figure 14.- Continued.



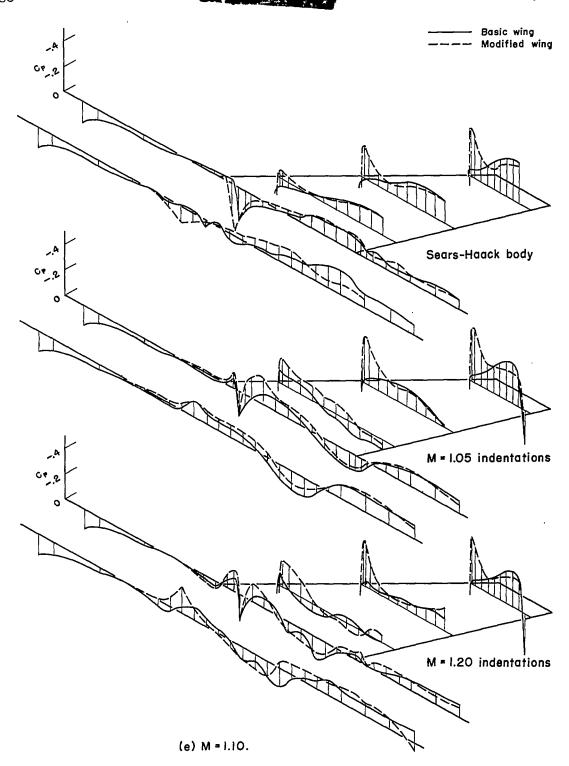


Figure 14.- Continued.



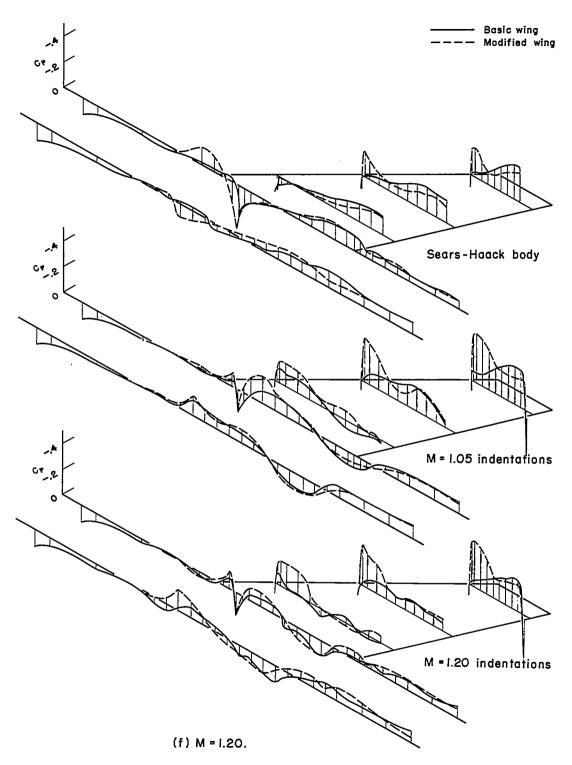


Figure 14.- Concluded.



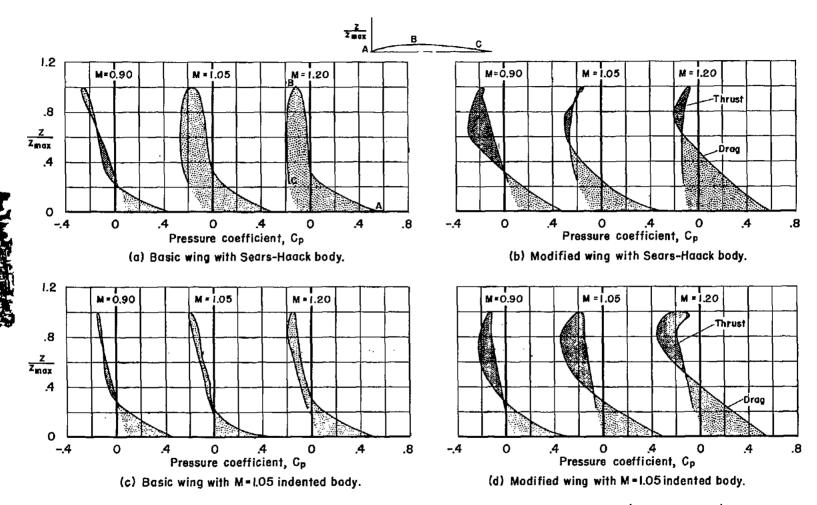


Figure 15.- Zero-lift pressure coefficients for the mid-semispan station (see fig. 13) and the upper surface of each wing plotted to illustrate the thrust and drag components of the streamwise airfoil sections.





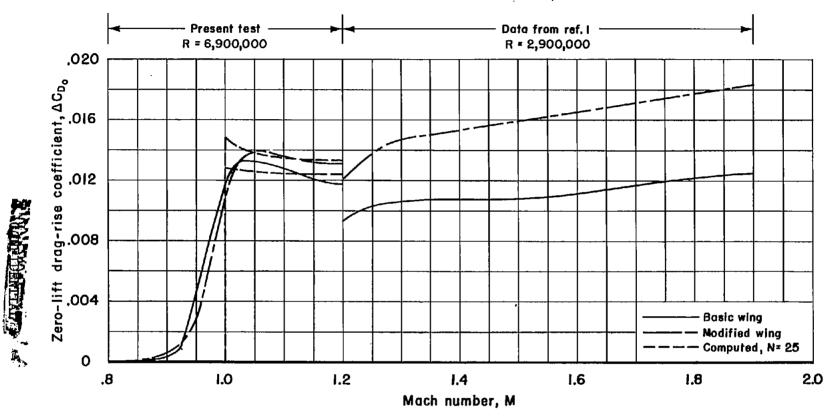
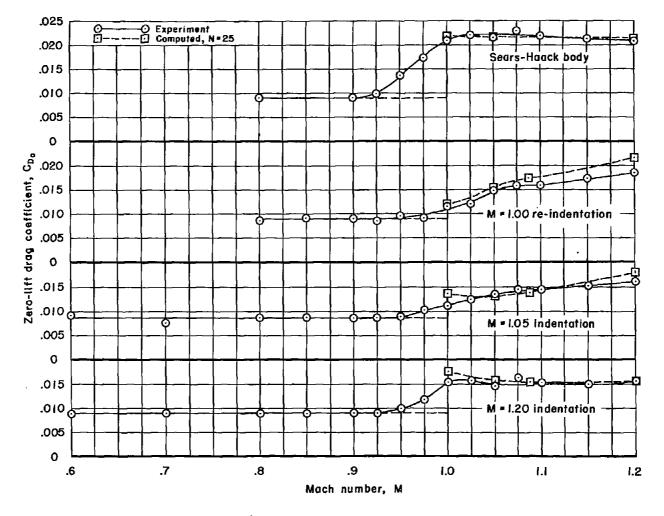
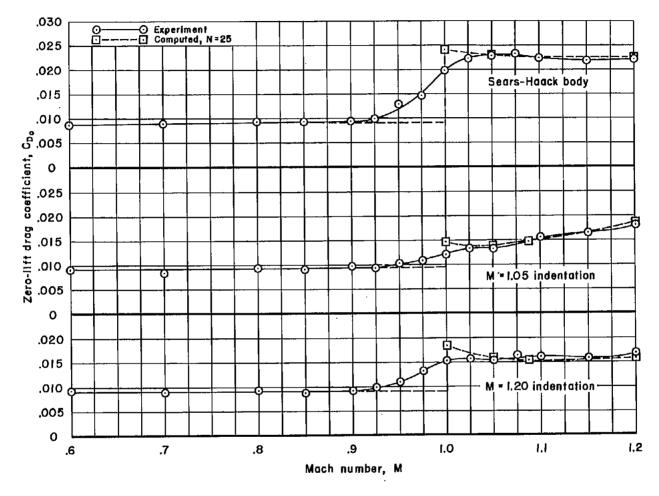


Figure 16.- Zero-lift drag-rise coefficients for the basic- and modified-wing models with the Sears-Haack body. (The modified wing of ref. 1 had slight forward camber.)



(a) Basic-wing models.

Figure 17.- Experimental and computed zero-lift drag coefficients for the two wing models with various bodies.



(b) Modified-wing models.

Figure 17.- Concluded.

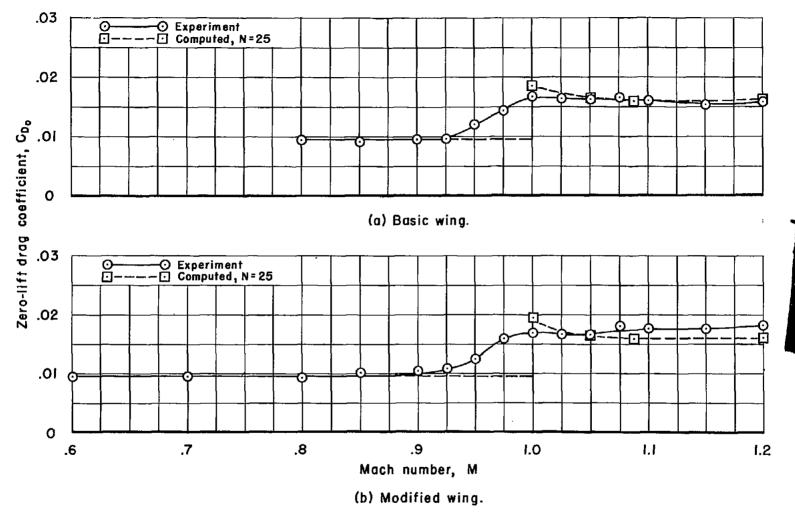


Figure 18.- Experimental and computed zero-lift drag coefficients for the basic- and modified-wing models with the M = 1.20 re-indented bodies.

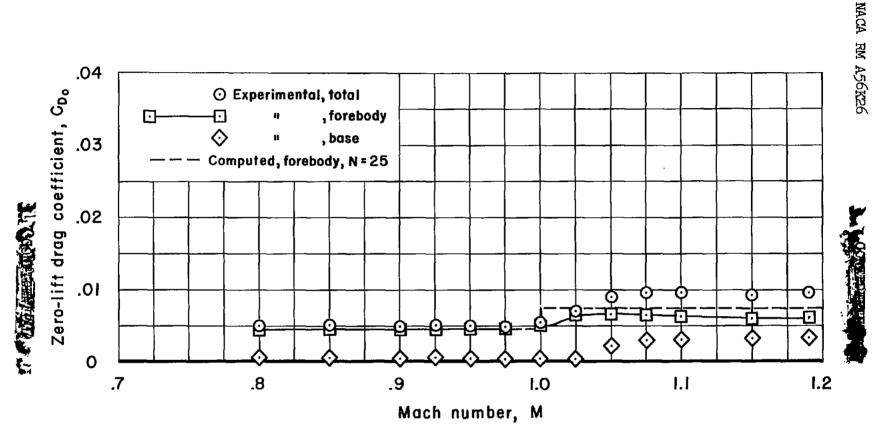


Figure 19.- Representative figure of base drag coefficients which were subtracted from the total values to obtain the forebody drag coefficients (Sears-Haack body alone).



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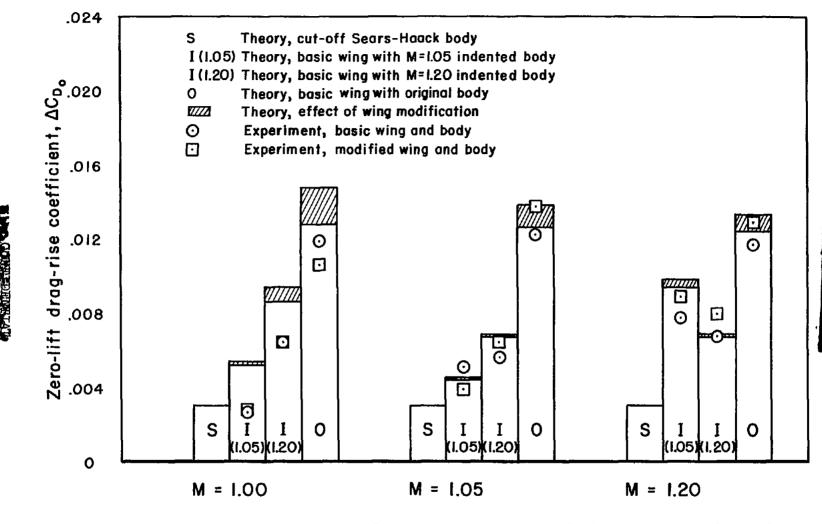
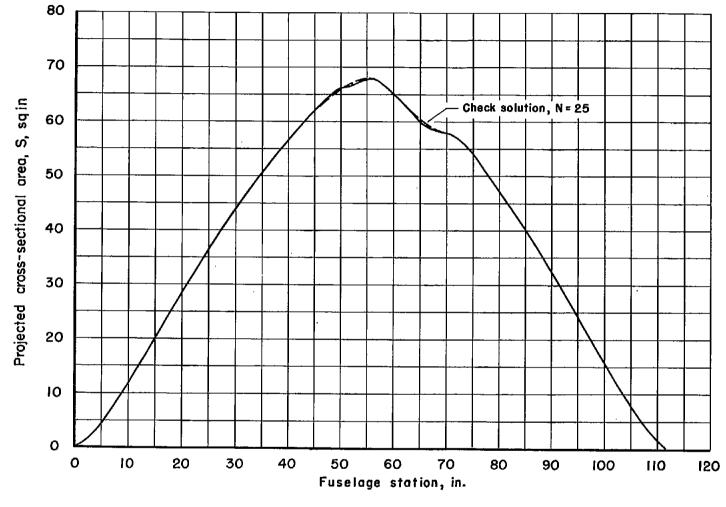


Figure 20.- Bar graph of computed zero-lift wave-drag coefficients for various models at three Mach numbers and the experimental drag-rise coefficient.

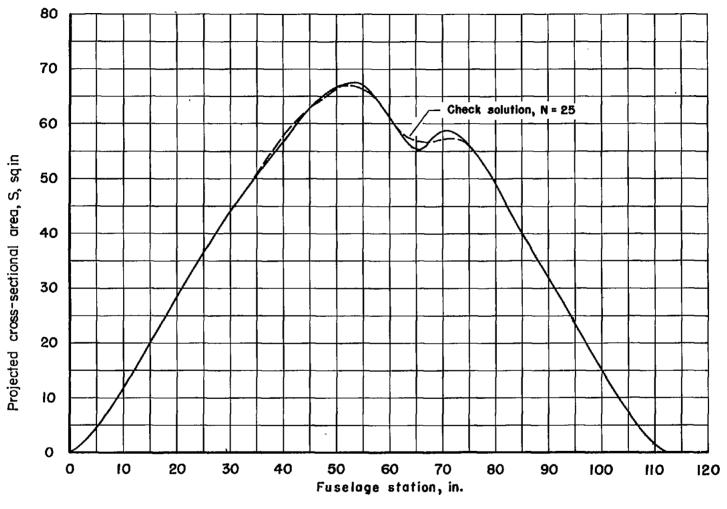
Figure 21.- Representative plots of the theoretical check solutions for N = 25 in comparison with the given area distributions (modified-wing model with M = 1.05 indented body).

(a) M = 1.20, $\theta = 90^{\circ}$, $\psi = 0^{\circ}$, and M = 1.00.



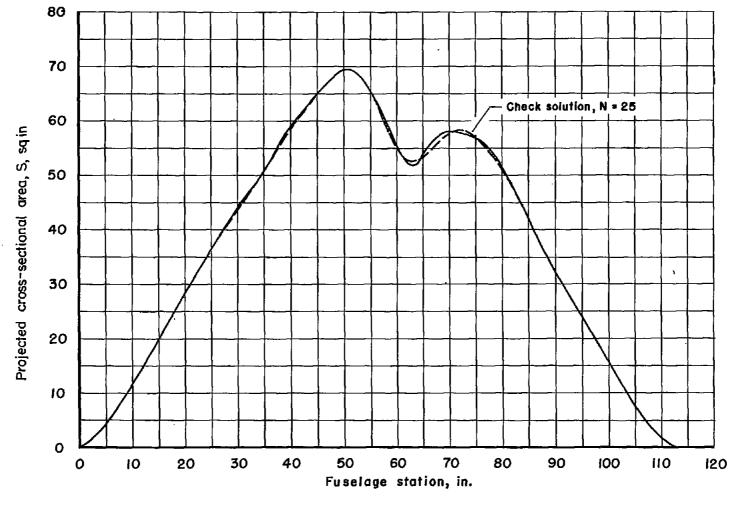
(b)
$$M = 1.20$$
, $\theta = 70^{\circ}$, $\psi = 12.75^{\circ}$

Figure 21.- Continued.



(c)
$$M = 1.20$$
, $\theta = 61.2^{\circ}$, $\psi = 17.75^{\circ}$

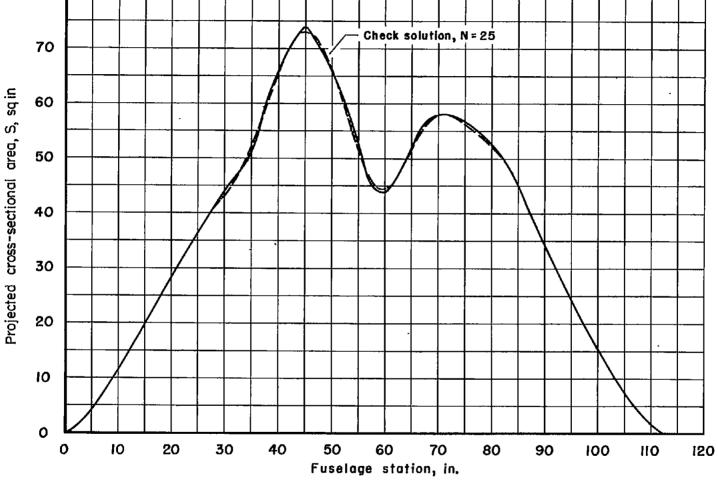
Figure 21.- Continued.



(d)
$$M = 1.20$$
, $\theta = 49.7^{\circ}$, $\psi = 23.2^{\circ}$

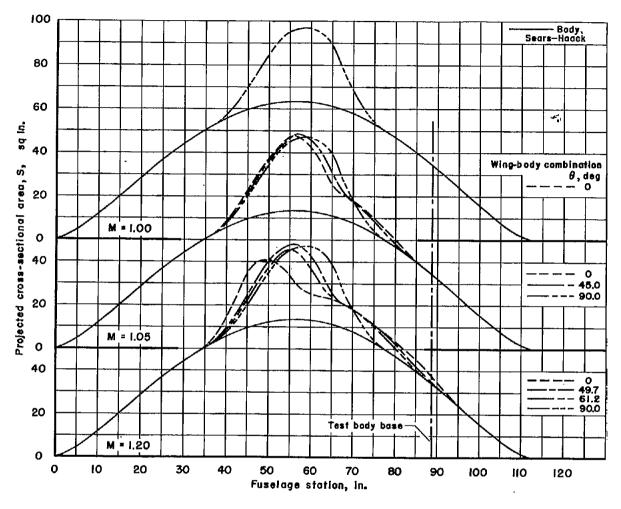
Figure 21.- Continued.

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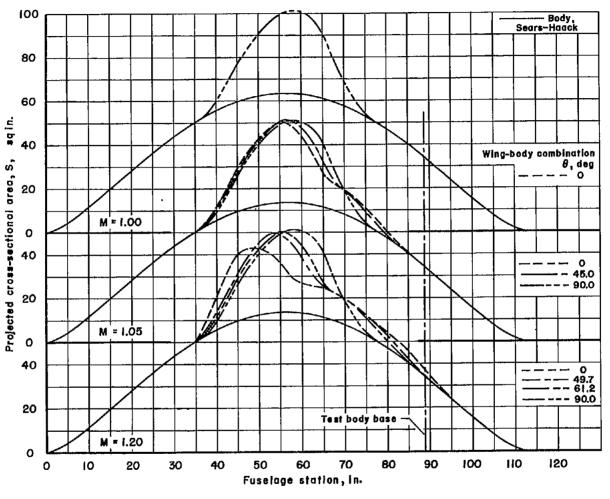
(e)
$$M = 1.20$$
, $\theta = 0^{\circ}$, $\psi = 33.6^{\circ}$

Figure 21.- Concluded



(a) Basic wing with Sears-Haack body.

Figure 22.- Variation of model area distributions with different cutting angles (θ) at Mach numbers of 1.00, 1.05, and 1.20.



(b) Modified wing with Sears-Haack body.

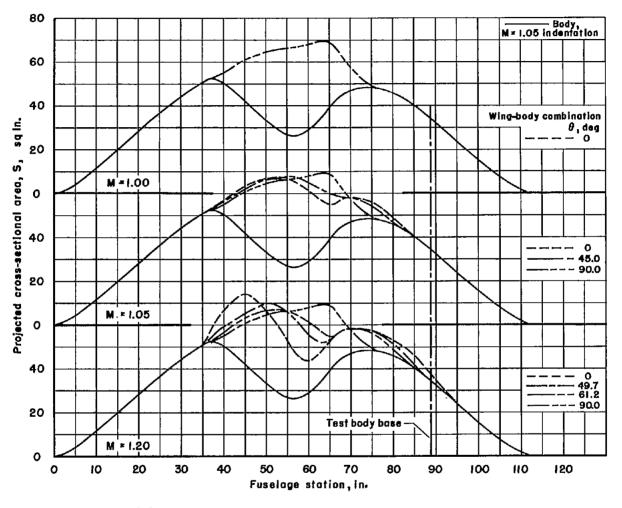
Figure 22.- Continued.

Body, M = 1.05 indentation

Figure 22.- Continued.

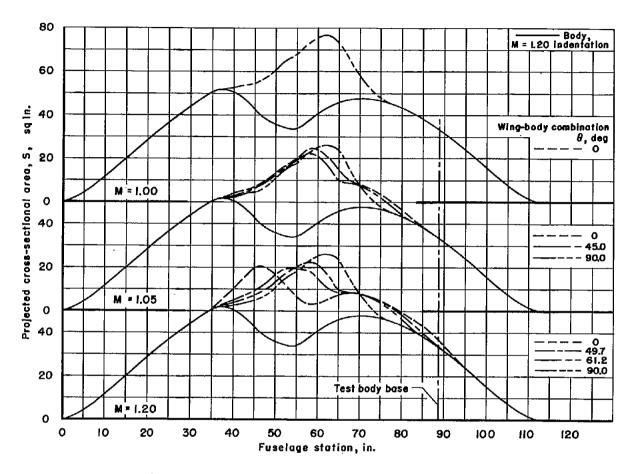
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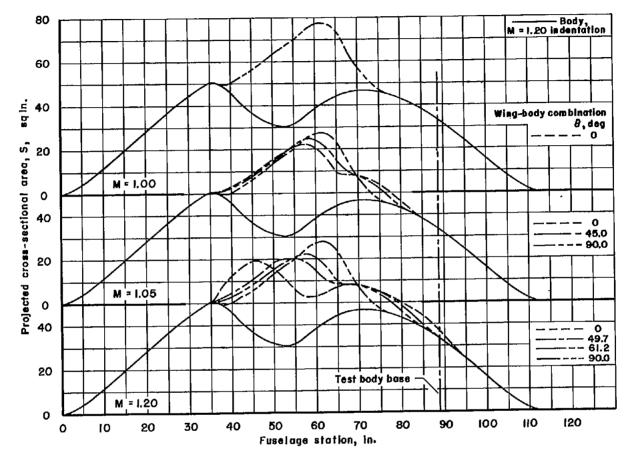
(d) Modified wing with M = 1.05 indented body.

Figure 22.- Continued.



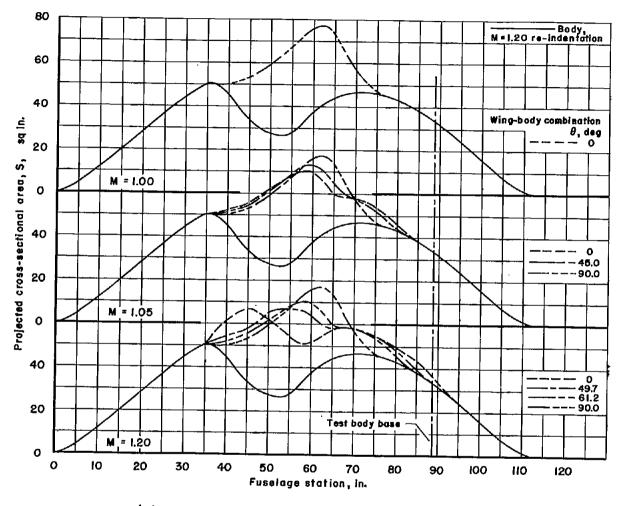
(e) Basic wing with M = 1.20 indented body.

Figure 22.- Continued.



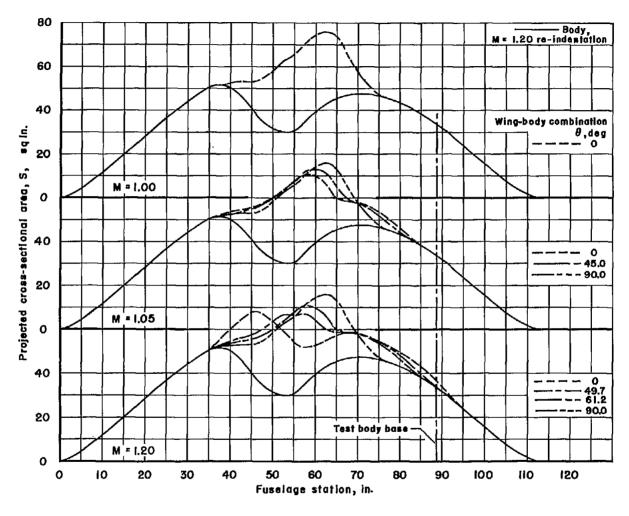
(f) Modified wing with M = 1.20 indented body.

Figure 22.- Continued.



(g) Basic wing with M = 1.20 re-indented body.

Figure 22.- Continued.



(h) Modified wing with M = 1.20 re-indented body.

Figure 22.- Concluded.

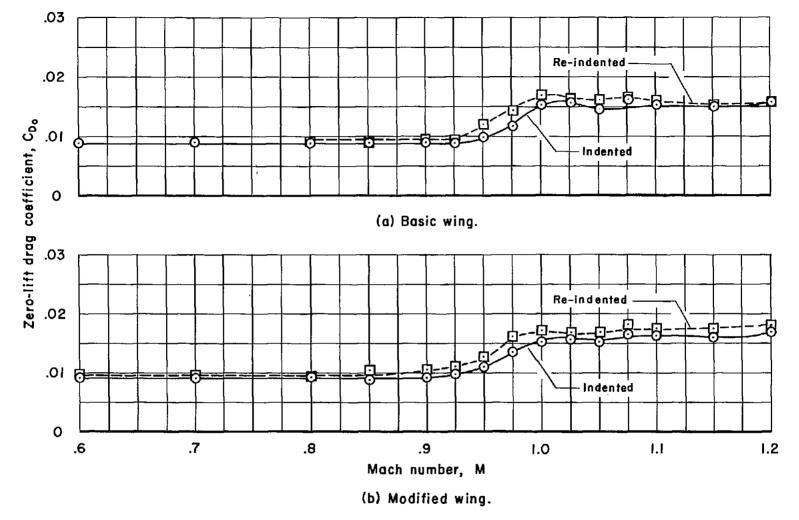


Figure 23.- Experimental zero-lift drag coefficients for the M = 1.20 indented and re-indented bodies with the basic and modified wings.

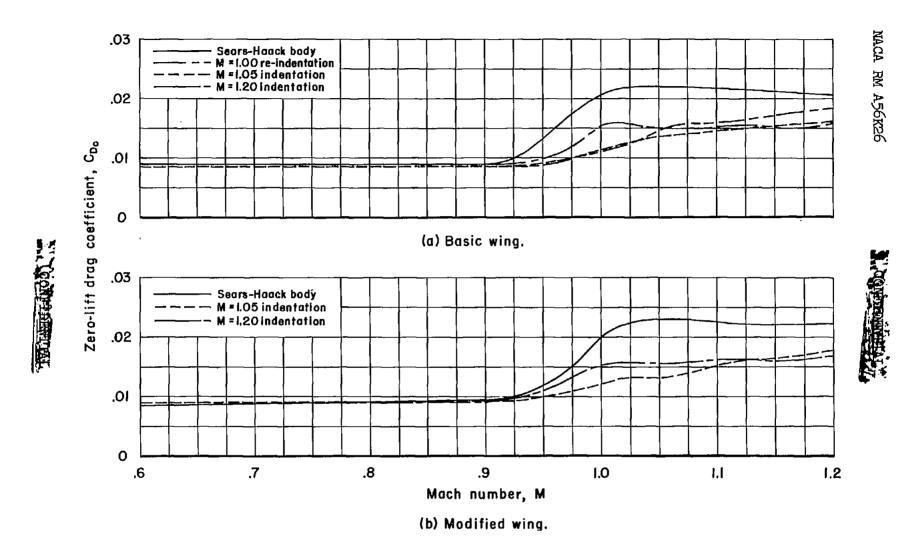


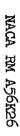
Figure 24.- Effect of various body indentations on the zero-lift drag coefficients for the basic-and modified-wing models.

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Sears-Haack body
M = 1.00 re-indentation

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Figure 25.- Effect of various body indentations on the maximum lift-drag ratios for the basicand modified-wing models.





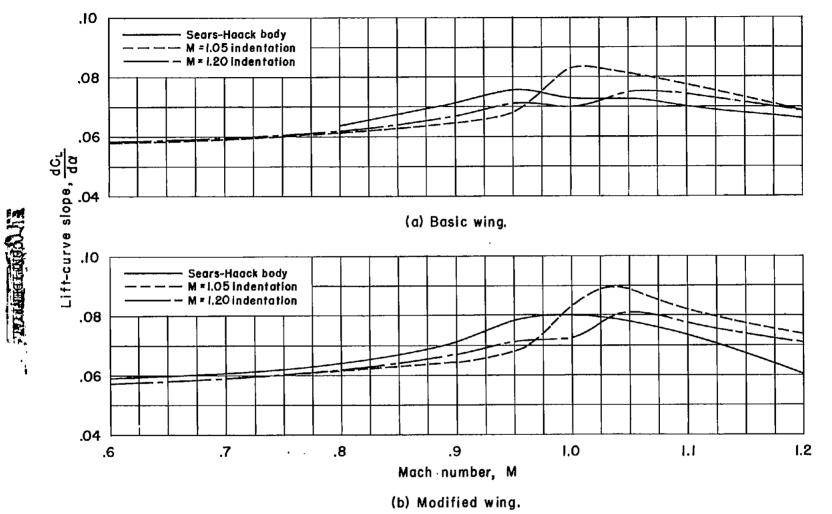


Figure 26.- Effect of various body indentations on the lift-curve slopes for the basic- and modified-wing models at low angles of attack.

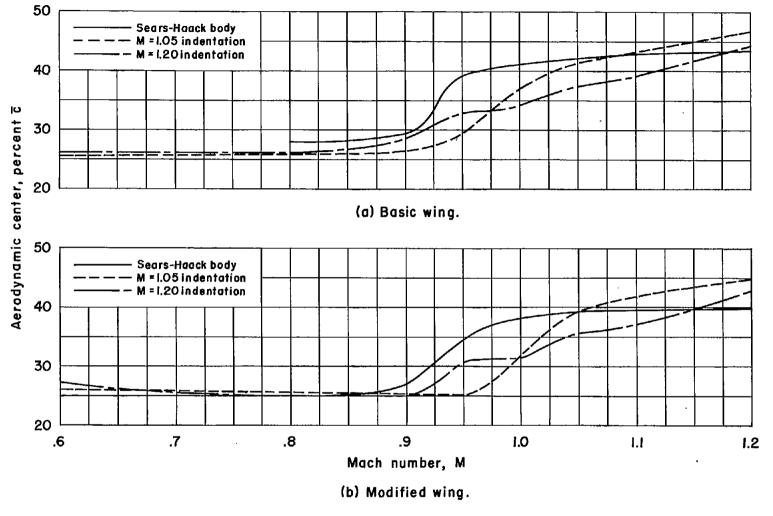
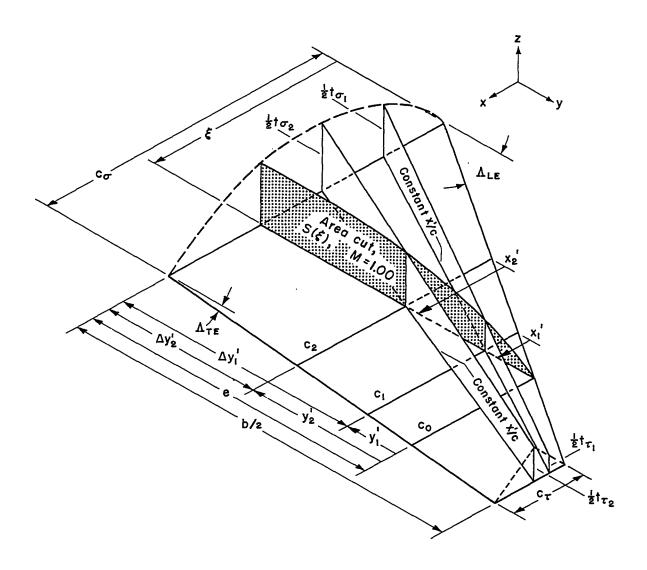


Figure 27.- Effect of various body indentations on the aerodynamic-center positions for the basic-and modified-wing models at low angles of attack.

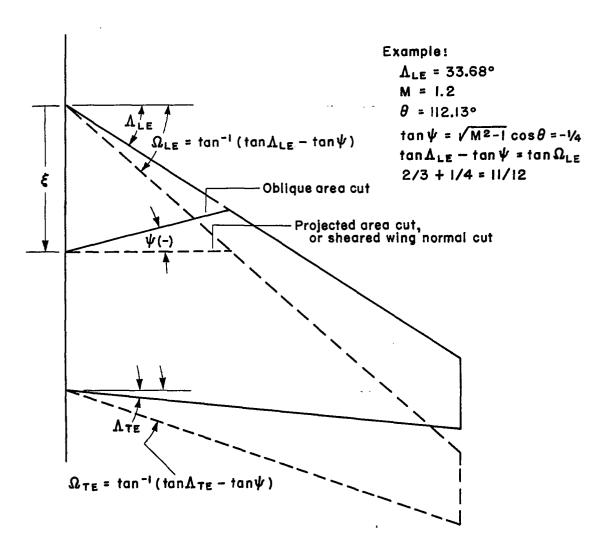




(a) Typical M = 1.00 area cut; upper half of wing panel.

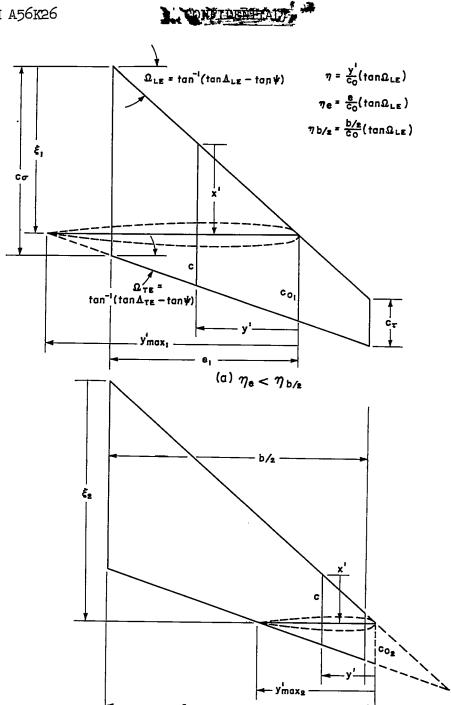
Figure 28.- Definition of primary dimension symbols used in Appendix B.





(b) The sheared wing for supersonic Mach numbers.

Figure 28.- Continued.



(c) Values of ξ , c_0 , y_{max}^{\dagger} for two locations on a typical wing. Figure 28.- Concluded.

(b) $\eta_{\rm e} > \eta_{\rm b/2}$

